

Lecture Notes “Introduction to Poisson Geometry”

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Introduction to Poisson Geometry

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Poisson 2014 Summer School

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Outline

- 1 Siméon-Denis Poisson
- 2 Jacobi, Lie and Lichnerowicz
- 3 Motivating examples
- 4 Plan for lectures 1 and 2
- 5 Plan for the remaining lectures

MÉMOIRE

Sur la Variation des Constantes arbitraires dans les questions de Mécanique,

Lu à l'Institut le 16 Octobre 1809;

Par M. POISSON.



ANALYSE.

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constante a ni la constante b ; dans d'autres cas elle ne contiendra aucune constante arbitraire, et se réduira à une constante déterminée; mais, afin de rappeler l'origine de cette quantité, qui représente une certaine combinaison des différences partielles des valeurs de a et b , nous ferons usage de cette notation (b, a) , pour la désigner; de manière que nous aurons généralement

$$\begin{aligned} \frac{db}{ds} \cdot \frac{da}{d\varphi} - \frac{da}{ds} \cdot \frac{db}{d\varphi} + \frac{db}{du} \cdot \frac{da}{d\psi} - \frac{da}{du} \cdot \frac{db}{d\psi} + \frac{db}{dv} \cdot \frac{da}{d\theta} \\ - \frac{da}{dv} \cdot \frac{db}{d\theta} = (b, a). \end{aligned}$$

Figure: Poisson bracket

Don't miss the Poisson exhibit!



Figure: Young Poisson and Yvette Kosmann-Schwarzbach



Figure: Siméon-Denis Poisson, Les mathématiques au service de la science. Exhibit in Paris (March-June 2014).

Jacobi, Lie and Lichnerowicz



Figure: Jacobi, Lie and Lichnerowicz

Example 1: Lie algebras of matrix groups

The operation on matrices $[A, B] = AB - BA$ is antisymmetric and satisfies $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$, (Jacobi).

Example: $SO(3, \mathbb{R}) = \{A \in GL(3, \mathbb{R}), \quad A^T A = Id, \quad \det(A) = 1\}$ and $\mathfrak{so}(3, \mathbb{R}) := T_{Id}(SO(3, \mathbb{R})) = \{A \in M(3, \mathbb{R}), \quad A^T + A = 0, \quad Tr(A) = 0\}$.

The brackets are determined on a basis

$$e_1 := \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad e_2 := \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \quad e_3 := \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

by $[e_1, e_2] = -e_3$, $[e_1, e_3] = e_2$, $[e_2, e_3] = -e_1$.

Define the (Poisson) bracket using the dual basis x_1, x_2, x_3 in $\mathfrak{so}(3, \mathbb{R})^*$

$$\{x_1, x_2\} = -x_3, \quad \{x_1, x_3\} = x_2, \quad \{x_2, x_3\} = -x_1$$

It satisfies Jacobi $\{x_i, \{x_j, x_k\}\} + \{x_j, \{x_k, x_i\}\} + \{x_k, \{x_i, x_j\}\} = 0$

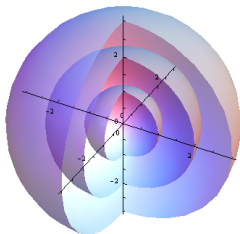
From Lie algebras to Poisson structures (Exercise 4)

Another way to write the Poisson bracket

$$-x_3 \frac{\partial}{\partial x_1} \wedge \frac{\partial}{\partial x_2} + x_2 \frac{\partial}{\partial x_1} \wedge \frac{\partial}{\partial x_3} - x_1 \frac{\partial}{\partial x_2} \wedge \frac{\partial}{\partial x_3}$$

Using the properties of the Poisson bracket,

$\{x_1^2 + x_2^2 + x_3^2, x_i\} = 0, i = 1, 2, 3$ and the function $f = x_1^2 + x_2^2 + x_3^2$ is a **constant of motion**.



Each sphere is endowed with an area form (**symplectic structure**).

Example 2: Determinants in \mathbb{R}^3 (Exercise 12)

- **Dynamics:** Given two functions $H, K \in \mathcal{C}^\infty(\mathbb{R}^3)$. Consider the system of differential equations:

$$(\dot{x}, \dot{y}, \dot{z}) = dH \wedge dK \quad (1)$$

H and K are constants of motion (the flow lies on $H = cte.$ and $K = cte.$)

- **Geometry:** Consider the brackets,

$$\{f, g\}_H := \det(df, dg, dH) \quad \{f, g\}_K := \det(df, dg, dK)$$

They are antisymmetric and satisfy Jacobi,

$$\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0.$$

The flow of the vector field

$$\{K, \cdot\}_H := \det(dK, \cdot, dH)$$

and $\{-H, \cdot\}_K$ is given by the differential equation (1) and

$$\{H, K\}_H = 0, \quad \{H, K\}_K = 0$$

Example 3: Hamilton's equations

The equations of the movement of a particle can be written as Hamilton's equation using the change $p_i = \dot{q}_i$,



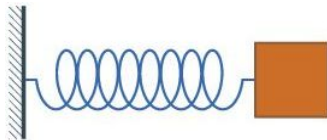
$$\begin{aligned}\dot{q} &= \frac{\partial H}{\partial p} \\ \dot{p} &= -\frac{\partial H}{\partial q}\end{aligned}$$

There is a **geometrical structure** behind this formula \rightsquigarrow **symplectic form** ω (closed non-degenerate 2-form).

Non-degeneracy \rightsquigarrow for every smooth function f , there exists a unique vector field X_f (Hamiltonian vector field),

$$i_{X_f}\omega = -df$$

Example 4: Coupling two simple harmonic oscillators



The phase space is $(T^*(\mathbb{R}^2), \omega = dx_1 \wedge dy_1 + dx_2 \wedge dy_2)$. H is the sum of potential and kinetic energy,

$$H = \frac{1}{2}(y_1^2 + y_2^2) + \frac{1}{2}(x_1^2 + x_2^2)$$

$H = h$ is a sphere S^3 . We have rotational symmetry on this sphere \rightsquigarrow the angular momentum is a constant of motion, $L = x_1 y_2 - x_2 y_1$, $X_L = (-x_2, x_1, -y_2, y_1)$ and

$$X_L(H) = \{L, H\} = 0.$$

Example 5: Cauchy-Riemann equations and Hamilton's equations

- Take a holomorphic function on $F : \mathbb{C}^2 \longrightarrow \mathbb{C}$ decompose it as $F = G + iH$ with $G, H : \mathbb{R}^4 \longrightarrow \mathbb{R}$.

Cauchy-Riemann equations for F in coordinates $z_j = x_j + iy_j$, $j = 1, 2$

$$\frac{\partial G}{\partial x_i} = \frac{\partial H}{\partial y_i}, \quad \frac{\partial G}{\partial y_i} = -\frac{\partial H}{\partial x_i}$$

- Reinterpret these equations as the equality

$$\{G, \cdot\}_0 = \{H, \cdot\}_1$$

with $\{\cdot, \cdot\}_j$ the Poisson brackets associated to the real and imaginary part of the symplectic form $\omega = dz_1 \wedge dz_2$ ($\omega = \omega_0 + i\omega_1$).

- Check $\{G, H\}_0 = 0$ and $\{H, G\}_1 = 0$ (integrable system).

Plan for the first 2 lectures

- Definition and examples.
- Weinstein's splitting theorem and symplectic foliation.

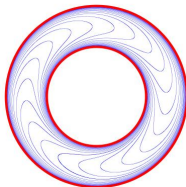


Figure: Alan Weinstein and Reeb foliation

- Normal form theorems.



Figure: Marius Crainic, Rui Loja Fernandes and Ionut Marcu

Plan for the remaining lectures

- Global aspects: Poisson cohomology and modular class.
- Compatible Poisson structures and integrable systems.
- Hamiltonian group actions and integrable systems.
- Action-angle coordinates on Poisson manifolds.

Introduction to Poisson Geometry- Lecture 3

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Schouten Bracket of vector fields in local coordinates

- Case of vector fields,

$A = \sum_i a_i \frac{\partial}{\partial x_i}$ and $B = \sum_i b_i \frac{\partial}{\partial x_i}$. Then

$$[A, B] = \sum_i a_i \left(\sum_j \frac{\partial b_j}{\partial x_i} \frac{\partial}{\partial x_j} \right) - \sum_i b_i \left(\sum_j \frac{\partial a_j}{\partial x_i} \frac{\partial}{\partial x_j} \right)$$

- Re-denoting $\frac{\partial}{\partial x_i}$ as ζ_i (**“odd coordinates”**).

Then $A = \sum_i a_i \zeta_i$ and $B = \sum_i b_i \zeta_i$ and $\zeta_i \zeta_j = -\zeta_j \zeta_i$. Now we can reinterpret the bracket as,

$$[A, B] = \sum_i \frac{\partial A}{\partial \zeta_i} \frac{\partial B}{\partial x_i} - \sum_i \frac{\partial B}{\partial \zeta_i} \frac{\partial A}{\partial x_i}$$

Schouten Bracket of multivector fields in local coordinates

We reproduce the same scheme for the case of multivector fields.

$$[A, B] = \sum_i \frac{\partial A}{\partial \zeta_i} \frac{\partial B}{\partial x_i} - (-1)^{(a-1)(b-1)} \sum_i \frac{\partial B}{\partial \zeta_i} \frac{\partial A}{\partial x_i}$$

is a $(a + b - 1)$ -vector field.

where

$$A = \sum_{i_1 < \dots < i_a} A_{i_1, \dots, i_a} \frac{\partial}{\partial x_{i_1}} \wedge \dots \wedge \frac{\partial}{\partial x_{i_a}} = \sum_{i_1 < \dots < i_a} A_{i_1, \dots, i_a} \zeta_{i_1} \dots \zeta_{i_a}$$

and

$$B = \sum_{i_1 < \dots < i_b} B_{i_1, \dots, i_b} \frac{\partial}{\partial x_{i_1}} \wedge \dots \wedge \frac{\partial}{\partial x_{i_b}} = \sum_{i_1 < \dots < i_b} B_{i_1, \dots, i_b} \zeta_{i_1} \dots \zeta_{i_b}$$

with $\frac{\partial(\zeta_{i_1} \dots \zeta_{i_p})}{\partial \zeta_{i_k}} := (-1)^{(p-k)} \eta_{i_1} \dots \hat{\eta}_{i_k} \eta_{i_{p-1}}$

Theorem (Schouten-Nijenhuis)

The bracket defined by this formula satisfies,

Graded anti-commutativity $[A, B] = -(-1)^{(a-1)(b-1)}[B, A]$.

Graded Leibniz rule

$$[A, B \wedge C] = [A, B] \wedge C + (-1)^{(a-1)b} B \wedge [A, C]$$

Graded Jacobi identity

$$(-1)^{(a-1)(c-1)}[A, [B, C]] + (-1)^{(b-1)(a-1)}[B, [C, A]] + (-1)^{(c-1)(b-1)}[C, [A, B]] = 0$$

If X is a vector field then, $[X, B] = L_X B$.

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Introduction to Poisson Geometry

Lecture 4 (Integrable Systems)

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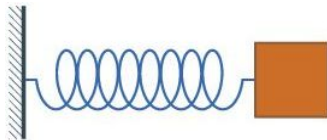
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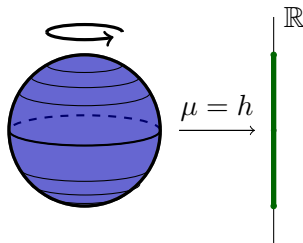
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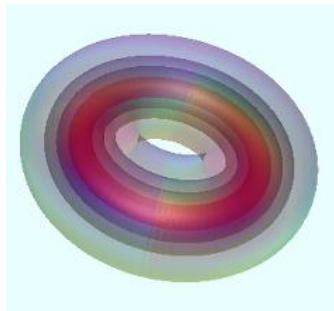
Topology of integrable systems (Symplectic case)

An integrable system on a surface.



The invariant submanifolds are tori (Liouville tori)

Lioville-Mineur-Arnold theorem (Symplectic manifolds)



The orbits of an integrable system in a neighbourhood of a compact orbit are tori. In **action-angle** coordinates (p_i, θ_i) the foliation is given by the fibration $\{p_i = c_i\}$ and the symplectic structure is Darboux

$$\omega = \sum_{i=1}^n dp_i \wedge d\theta_i.$$

The characters of the day

Joseph Liouville proved that the invariant manifolds were tori.



Figure: Joseph Liouville, Henri Mineur, Duistermaat and Arnold

Henri Mineur gave an explicit formula for action coordinates: $p_i = \int_{\gamma_i} \alpha$ where γ_i is one of the cycles of the Liouville torus and α is a Liouville 1-form for the symplectic structure ($\omega = d\alpha$).

We will follow the proof by Duistermaat and apply it to Poisson manifolds.

What is an integrable system on a Poisson manifold?

Let (M, Π) be a Poisson manifold of (maximal) rank $2r$ and of dimension n . An s -tuple of functions $\mathbf{F} = (f_1, \dots, f_s)$ on M is said to define a **Liouville integrable system** on (M, Π) if

- ① f_1, \dots, f_s are independent ($df_1 \wedge \dots \wedge df_s \neq 0$).
- ② f_1, \dots, f_s are pairwise in involution
- ③ $r + s = n$

Viewed as a map, $\mathbf{F} : M \rightarrow \mathbb{R}^s$ is called the **moment map** of (M, Π) .

A Darboux-Carathéodory theorem in the Poisson context

Theorem (Laurent, M., Vanhaecke)

Let p_1, \dots, p_r be r functions in involution and whose Hamiltonian vector fields are linearly independent at a point $m \in (M, \Pi)$. There exist locally functions $q_1, \dots, q_r, z_1, \dots, z_{n-2r}$, such that

- 1 The n functions $(p_1, q_1, \dots, p_r, q_r, z_1, \dots, z_{n-2r})$ form a system of coordinates on U , centered at m ;
- 2 The Poisson structure Π is given on U by

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial q_i} \wedge \frac{\partial}{\partial p_i} + \sum_{i,j=1}^{n-2r} g_{ij}(z) \frac{\partial}{\partial z_i} \wedge \frac{\partial}{\partial z_j}, \quad (1)$$

An action-angle theorem for Poisson manifolds

Case of regular orbits

We assume that:

- 1 The mapping $\mathcal{F} = (f_1, \dots, f_s)$ defines an integrable system on the Poisson manifold (M, Π) of dimension n and (maximal) rank $2r$.
- 2 Suppose that $m \in M$ is a point such that it is regular for the integrable system and the Poisson structure.
- 3 Assume further than the integral manifold \mathcal{F}_m of the foliation X_{f_1}, \dots, X_{f_s} through m is compact (Liouville torus).

An action-angle theorem for Poisson manifolds

Theorem (Laurent, M., Vanhaecke)

There exist \mathbf{R} -valued smooth functions $(\sigma_1, \dots, \sigma_s)$ and \mathbf{R}/\mathbf{Z} -valued smooth functions $(\theta_1, \dots, \theta_r)$, defined in a neighborhood of \mathcal{F}_m such that

- ① *The functions $(\theta_1, \dots, \theta_r, \sigma_1, \dots, \sigma_s)$ define a diffeomorphism $U \simeq \mathbf{T}^r \times B^s$;*
- ② *The Poisson structure can be written in terms of these coordinates as*

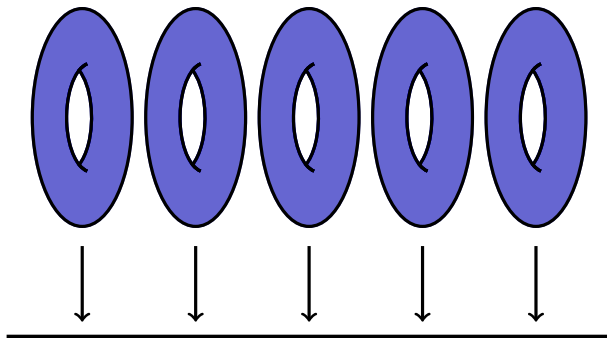
$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial \theta_i} \wedge \frac{\partial}{\partial \sigma_i},$$

in particular the functions $\sigma_{r+1}, \dots, \sigma_s$ are locally Casimirs of Π ;

- ③ *The leaves of the surjective submersion $\mathcal{F} = (f_1, \dots, f_s)$ are given by the projection onto the second component $\mathbf{T}^r \times B^s$, in particular, the functions $\sigma_1, \dots, \sigma_s$ depend only on the functions f_1, \dots, f_s .*

The Poisson proof

- **Step 1: Topology of the foliation.** The fibration in a neighbourhood of a compact connected fiber is a trivial fibration by compact fibers.



The Poisson proof

- **Step 2: These compact fibers are tori:** We recover a \mathbb{T}^r -action tangent to the leaves of the foliation. This implies a process of uniformization of periods.

$$\begin{aligned}\Phi &: \mathbf{R}^r \times (\mathbf{T}^r \times B^s) \rightarrow \mathbf{T}^r \times B^s \\ ((t_1, \dots, t_r), m) &\mapsto \Phi_{t_1}^{(1)} \circ \dots \circ \Phi_{t_r}^{(r)}(m).\end{aligned}\tag{2}$$

- **Step 3:** We prove that **this action is Poisson** (if Y is a complete vector field of period 1 and P is a bivector field for which $\mathcal{L}_Y^2 P = 0$, then $\mathcal{L}_Y P = 0$).
- **Step 4:** Finally we use the Poisson Cohomology of the manifold and averaging with respect to this action to check that **the action is Hamiltonian**.
- **Step 5:** To construct action-angle coordinates we use Darboux-Carathéodory and the constructed Hamiltonian action of \mathbb{T}^n to **drag normal forms from a neighbourhood of a point to a neighbourhood of a fiber**.

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What is a non-commutative integrable system on a Poisson manifold?

Definition

Let (M, Π) be a Poisson manifold of dimension n . An s -uplet of functions $\mathcal{F} = (f_1, \dots, f_s)$ is said to be a *non-commutative integrable system of rank r* on (M, Π) if

- (1) f_1, \dots, f_s are independent;
- (2) The functions f_1, \dots, f_r are in involution with the functions f_{r+1}, \dots, f_s ;
- (3) $r + s = n$;
- (4) The Hamiltonian vector fields of the functions f_1, \dots, f_r are linearly independent at some point of M .

Notice that $2r \leq \text{Rk } \Pi$, as a consequence of (4).

Remark: The mapping $\mathcal{F} = (f_1, \dots, f_s)$ is a Poisson map on \mathbb{R}^s with \mathbb{R}^s endowed with a non-vanishing Poisson structure.

An action-angle theorem for non-commutative systems

Theorem (Laurent, M., Vanhaecke)

Suppose that \mathcal{F}_m is a regular Liouville torus. Then there exist semilocally \mathbf{R} -valued smooth functions $(p_1, \dots, p_r, z_1, \dots, z_{s-r})$ and \mathbf{R}/\mathbf{Z} -valued smooth functions $(\theta_1, \dots, \theta_r)$ such that,

- 1 The functions $(\theta_1, \dots, \theta_r, p_1, \dots, p_r, z_1, \dots, z_{s-r})$ define a diffeomorphism $U \simeq \mathbf{T}^r \times B^s$;
- 2 The Poisson structure can be written in terms of these coordinates as

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial \theta_i} \wedge \frac{\partial}{\partial p_i} + \sum_{k,l=1}^{s-r} \phi_{k,l}(z) \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_l};$$

- 3 The leaves of the surjective submersion $\mathcal{F} = (f_1, \dots, f_s)$ are given by the projection onto the second component $\mathbf{T}^r \times B^s$, in particular, the functions $p_1, \dots, p_r, z_1, \dots, z_{s-r}$ depend on the functions f_1, \dots, f_s only.

Definition 1

A C^∞ -smooth Poisson structure is an \mathbb{R} -bilinear operation $\{ \cdot, \cdot \} : C^\infty(M) \times C^\infty(M) \rightarrow C^\infty(M)$ $(f, g) \mapsto \{f, g\}$ which satisfies

- ① skew-symmetry: $\{f, g\} = -\{g, f\} \quad \forall f, g \in C^\infty(M)$
- ② Leibnitz rule: $\{f, g_1 g_2\} = \{f, g_1\} g_2 + g_1 \{f, g_2\} \quad \forall f, g_1, g_2 \in C^\infty(M)$
- ③ Jacobi identity: $\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0$
 $\forall f, g, h \in C^\infty(M)$

Example 0

Any manifold (orientable or not). Define $\{f, g\} = 0 \quad \forall f, g \in C^\infty(M) \Rightarrow$ Any smooth manifold admits a Poisson structure (perhaps a little boring). In particular, there are no top. obstructions to the existence of a Poisson structure.

Example 1

(Symplectic manifolds) (M, ω) a symplectic manifold. ω is a 2-form, closed ($d\omega = 0$) and non-degenerate, i.e. $L_X \omega = \alpha$ always has a solution.

Notice that M has to be even-dimensional because of non-degeneracy.

Define $\{f, g\} = \omega(X_f, X_g)$, where X_f is the (unique) solution of the equation $L_{X_f} \omega = -df$.

① Skew-symmetry: $\{f, g\} = \omega(X_f, X_g) = -\omega(X_g, X_f) = -\{g, f\}$

② Leibnitz: $\{f, g\} = \omega(X_f, X_g) = L_{X_f} \omega(X_g) = -df(X_g) = -X_g(f)$

Using skew-symmetry, $\{f, g\} = -\{g, f\} = X_f(g)$. Since X_f is a derivation, we obtain Leibnitz.

③ Jacobi: exercise

Remark

locally, all symplectic manifolds look the same

Let (M, ω) be a symplectic manifold. There exist local coordinates $(x_1, y_1, \dots, x_n, y_n)$ on (M, ω) such that, locally,

$$\omega = \sum_{i=1}^n dx_i \wedge dy_i$$

In Darboux coordinates, $\{f, g\} = X_f(g) = \dots = \sum_{i=1}^n \frac{\partial f}{\partial x_i} \frac{\partial g}{\partial y_i} - \frac{\partial f}{\partial y_i} \frac{\partial g}{\partial x_i}$

This is the same expression that Poisson gave in his original paper for a 4-manifold.

$(\mathbb{R}^2, \{\cdot, \cdot\})$. Define $\{f, g\} = H(x, y) \cdot \left(\frac{\partial f}{\partial x} \frac{\partial g}{\partial y} - \frac{\partial f}{\partial y} \frac{\partial g}{\partial x} \right)$

Example 2

In exercise 2 we show that the Hamiltonian vector field for this new bracket is $X_f^{\text{tilde}} = H(x, y) X_f^{\text{can}}$, where X_f^{can} is the Hamiltonian vector field of the canonical Poisson bracket in \mathbb{R}^2 .

• The Jacobi identity comes for free.

• $H(x, y) = \text{const.} \iff$ symplectic structure

• Arnold classification of functions on the plane \Rightarrow if

$H(x, y)$ is regular, locally $H(x, y) = x$. Hence

$$\{f, g\} = x \left(\frac{\partial f}{\partial x} \frac{\partial g}{\partial y} - \frac{\partial f}{\partial y} \frac{\partial g}{\partial x} \right)$$

$x \neq 0 \Rightarrow$ symplectic

$x = 0 \Rightarrow$ Example 0

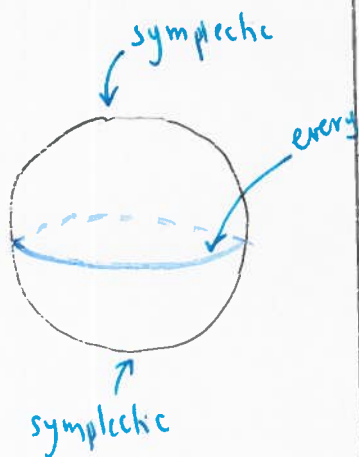
b-symplectic
or
log-symplectic

$(S^2, \{\cdot, \cdot\})$. In coordinates (h, θ) , we set

$$\{f, g\} = h \{f, g\}_{\text{can}}$$

where $\{f, g\}_{\text{can}}$ is the canonical Poisson structure

Sub-example



Name: _____

Seite: 2

There is a whole hierarchy. The next level when studying the Arnold classification is

$$\{f, g\} = xy \{f, g\}_{\text{can.}}$$

This gives c-symplectic / log-symplectic structures (Gualtieri, Li, Pelayo, Ratiu).

SPLITTING THEOREM & NORMAL FORMS

LOCAL COORDINATES

Let $(M, \{\cdot, \cdot\})$ be a Poisson manifold. Take a coordinate system (x_1, \dots, x_n) on M . Set $w_{ij} = \{x_i, x_j\}$.

The functions w_{ij} have the following properties:

① skew-symmetry $w_{ij} = -w_{ji}$

② Jacobi: $\{w_{ij}, x_k\} + \{w_{jk}, x_i\} + \{w_{ki}, x_j\} = 0$

• (Leibniz)

$$(***) \quad \sum_{l=1}^n \left(w_{il} \frac{\partial w_{jk}}{\partial x_l} + w_{jl} \frac{\partial w_{ik}}{\partial x_l} + w_{kl} \frac{\partial w_{ij}}{\partial x_l} \right) = 0 \quad \forall i, j, k$$

This gives a set of equations that have to be verified.

$$\leadsto \{f, g\} = [df]^t w [dg] \quad \text{where } w = (w_{ij})_{ij}$$

Conversely, given a skew-symmetric matrix $w = (w_{ij})_{ij}$, the formula

$$\{f, g\} = \sum_{i, j=1}^n w_{ij} \frac{\partial f}{\partial x_i} \frac{\partial g}{\partial x_j}$$

defines a Poisson bracket if w satisfies (***)

Example 1 (w_{ij}) linear functions $\Rightarrow w_{ij} = \sum_{k=1}^n C_{ij}^k x_k$, C_{ij}^k constants

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If the coordinates are global, $\omega_{ij} = \sum_{k=1}^n c_{ij}^k x_k$ satisfies $(\omega, \omega, \omega) \Leftrightarrow c_{ij}^k$ are the structural constants of a (dual) of a Lie algebra.

ω_{ij} constants \Rightarrow regular Poisson structure; this is because, looking at ω_{ij} as a tensor on our manifold, this tensor has constant rank (already known to be).

Example 2

9 THE LANGUAGE OF BIVECTORS

(M, ω) symplectic \longleftrightarrow forms, $d\omega = 0$

Let $(M, \{\cdot, \cdot\})$ be a Poisson manifold. In order to handle more effectively with Poisson manifolds, I have to handle simultaneously with a collection of symplectic manifolds (see example of two half-spheres). The appropriate language for this is that of bivector fields, $\Pi \in \Gamma(\Lambda^2 TM)$. The idea is that I need a "bivector", since the Poisson bracket is a derivation in two arguments.

In local coordinates: $\Pi = \sum \Pi_{ij} \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial x_j}$, $\Pi_{ij} \in C^\infty(M)$.

Given a Poisson manifold $(M, \{\cdot, \cdot\})$, $\exists \Pi \in \Lambda^2 TM$ such that

$$\{f, g\} = \Pi(df, dg)$$

Proposition 1

Proof The local dependence gives immediately Π . How do I construct it? Locally, the coefficients are $\Pi_{ij} = \omega_{ij} = \langle x_i, x_j \rangle$.

Proposition 2Given a bivector field Π , the formula

$$\{f, g\}_\Pi = \Pi(df, dg) \quad (*)$$

is \mathbb{R} -bilinear, skew-symmetric and satisfies Leibniz.(For Leibniz: $\{f, \cdot\}_\Pi = \Pi(df, \cdot) \Rightarrow$ vector field \Rightarrow derivation, hence satisfies Leibniz).Question

Does (*) satisfy Jacobi? NOT in general

Example

$$\Pi = \frac{\partial}{\partial x} \wedge \frac{\partial}{\partial y} + x \frac{\partial}{\partial x} \wedge \frac{\partial}{\partial z} \Leftrightarrow \{x, y\} = 1, \{x, z\} = x$$

If Jacobi were satisfied:

$$0 = \{\{x, y\}, z\} + \{\{y, z\}, x\} + \{\{z, x\}, y\} = -\{x, y\} = -1 !!$$

I need an additional condition on my bivector.

$$\boxed{[\Pi, \Pi] = 0} \quad \text{The Schouten bracket should vanish.}$$

We'll give a kit to actually compute Schouten bracket.

$$\left\{ \begin{array}{l} \Pi \text{ bivector} \\ [\Pi, \Pi] = 0 \end{array} \right\} \longleftrightarrow (M, \{\cdot, \cdot\})$$

Properties of $[\cdot, \cdot]$ $[\cdot, \cdot]$ is \mathbb{R} -bilinear; if $A \in \Gamma(\wedge^p TM)$, $B \in \Gamma(\wedge^q TM)$, then

$$[A, B] = -(-1)^{(p-1)(q-1)} [B, A].$$

$$\text{Graded Leibniz: } [A, B \wedge C] = [A, B] \wedge C + (-1)^{(p-1)q} B \wedge [A, C]$$

Exercise

$$\text{For } \Pi = \frac{\partial}{\partial x} \wedge \frac{\partial}{\partial z} + y \frac{\partial}{\partial x} \wedge \frac{\partial}{\partial y}, \text{ show } [\Pi, \Pi] = 0.$$

6 THE POISSON CATEGORY

Let $(M_1, \{\cdot, \cdot\}_1)$ and $(M_2, \{\cdot, \cdot\}_2)$ be Poisson manifolds.

A diffeomorphism $\phi: M_1 \rightarrow M_2$ is a Poisson morphism if

$$\phi^*(\{f, g\}_2) = \{\phi^*f, \phi^*g\}_1 \quad \forall f, g \in C^\infty(M_2).$$

Definition

$F: M \rightarrow \mathfrak{g}^*$ a moment map, where M is a Poisson manifold and \mathfrak{g}^* has the Poisson structure of Exercise 4.

Example 1

$\mathfrak{h} \xhookrightarrow{\iota} \mathfrak{g}$ inclusion of Lie algebras. The dual map

$\iota^*: \mathfrak{g}^* \rightarrow \mathfrak{h}^*$ is a Poisson morphism

(This is a special case of 1, and holds also for Lie algebra morphisms)

Example 2

(Poisson submanifolds) $(N, \pi_N) \xhookrightarrow{\iota} (M, \pi_M)$.

(N, π_N) is a Poisson submanifold if ι is a Poisson morphism.

Example 3

So far we have objects & maps in our category. What are the infinitesimal transformations?

A vector field X is a Poisson vector field $\Leftrightarrow L_X \pi = 0$

Definition

The flow of a Poisson vector field X is a Poisson morphism.

Remark

Is there a way to characterize Poisson vector fields in terms of the Poisson bracket?

$$L_X \pi = 0 \Leftrightarrow X(\{f, g\}) = \{X(f), g\} + \{f, X(g)\}$$

Remark

Definition

Let $(M, \{\cdot, \cdot\})$ be a Poisson manifold. A Hamiltonian vector field, associated to $f \in C^\infty(M)$, is $X_f = \{\cdot, f\}$

Remark

The Hamiltonian v.f. of f is also described by

$$X_f = \Pi(df, \cdot)$$

In symplectic geometry, the difference between symplectic and ~~vector~~^{HAMILTONIAN} vector fields is measured by de Rham cohomology. In Poisson geometry, this difference is measured by Poisson cohomology (to be introduced)

Properties

- 1) X_f is a Poisson vector field (Jacobi)
- 2) $X_f(f) = 0$ (skew-symmetry)
- 3) $[X_f, X_g] = X_{\{f, g\}}$ (**)

§ SYMPLECTIC FOLIATIONS & SPLITTING THEOREM

$(M, \{\cdot, \cdot\})$ a Poisson manifold.

$\mathcal{D} = \{X_f \mid f \in C^\infty(M)\}$ is a distribution (**)

Frobenius Theorem

\mathcal{D} regular involutive distribution $\Rightarrow \mathcal{D}$ integrable

Stefan-Sussman Theorem

Let \mathcal{C} be a family generating the distribution \mathcal{D} , such that \mathcal{D} is invariant under \mathcal{C} . Then \mathcal{D} is integrable, although the dimension of the integral submanifolds will, in general, jump from point to point.

Proposition

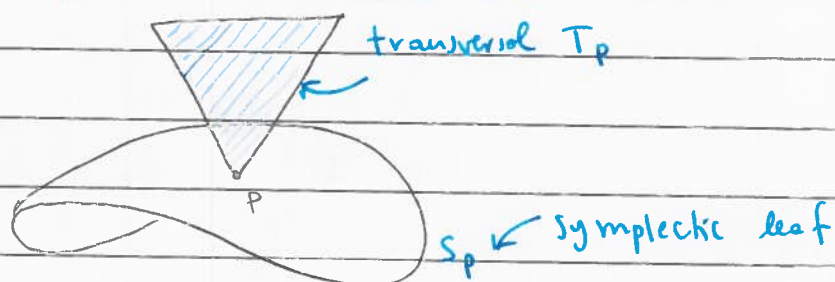
$\mathcal{D} = \{X_f \mid f \in C^\infty(M)\}$ satisfies the conditions of the Stefan-Sussman theorem. There exists \mathcal{F} (singular)

foliation integrating \mathcal{D} , and \mathcal{F} is symplectic.

On a Poisson manifold (M, Π) any point $p \in M$ has a coordinate system $(x_1, y_1, \dots, x_N, y_N, z_1, \dots, z_d)$ centered at p , such that

$$\Pi = \sum_{i=1}^N \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial y_i} + \sum_{i,j \in J} \psi_{ij}(z) \frac{\partial}{\partial z_i} \wedge \frac{\partial}{\partial z_j}$$

$\psi_{ij}(p) = 0$; $2N = \text{Rank}(\Pi(p))$ and $2N + d = m = \dim M$.



$$\Pi = \Pi_S + \Pi_T$$

↑ "inverse" of the symplectic form along S .

Π Poisson bivector $\Pi^\# : T^*M \longrightarrow TM$ is the anchor map (displaying T^*M as a Lie algebroid).
Here $\Pi^\#(\alpha) = \Pi(\alpha, \cdot)$

$$\mathcal{D}_p = \{X_f \mid f \in C^\infty(M)\}; \quad \mathcal{D}_p = \text{Im } \Pi^\#$$

$\text{Rank } \Pi(p) = \dim \Pi^\#_p = \text{dimension of the symplectic leaf through } p \in M$.

The normal form theorem doesn't say much about the transversal

Weinstein remarked that two different transversals are related by a Poisson diffeomorphism.

Theorem (Weinstein, 1983)

Picture

In other words, the transverse Poisson structure does not depend on the particular transversal, but only on the symplectic leaf.

SYMPLECTIC	POISSON
ω	Π
locally (Darboux):	locally (Weinstein)
$\omega = \sum_i dp_i \wedge dq_i$	$\Pi = \Pi_s + \Pi_r$

Weinstein theorem can be a bit frustrating: we don't know anything about the transversal. What are the functions ψ_i ?

Some proofs of the Weinstein theorem are new and use the notion of Poisson fibration, i.e. fibrations over a symplectic manifold with Poisson foliation.

There exist also equivariant normal forms, in case there is a group acting.

Theorem (Conn, 1985)

If the linear part of Π_T is semisimple of compact type*, then locally

$$\Pi = \sum_{i=1}^n \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial y_i} + \sum_{i,j,k} C_{ij}^k z^k \frac{\partial}{\partial z_i} \wedge \frac{\partial}{\partial z_j}$$

* ($\Pi_T^{(1)}$ = linear part) means: write $\psi_i = \sum C_{ij}^k z^k + O(z^2)$ in Weinstein theorem; if $\{C_{ij}^k\}$ happen to be the structure constants of a semisimple Lie algebra of compact type, then the theorem holds.

Remark

Compact type is needed! Counterexample: $5\ell(2, \mathbb{R})^*$

(see Weinstein '83, Guillemin - Sternberg)

- Crainic - Fernandes : geometric proof of Conn
- Crainic - Marcut : normal forms of symplectic leaves
- Stability of Poisson structures : Crainic - Fernandes - Marcut.

There's some cohomological condition related to retracts of g , namely $H^2(g, V) = 0 \forall g\text{-module } V$.

9 POISSON COHOMOLOGY

SYMPLECTIC

$$\omega \in \Omega^2(M) = \Gamma(\wedge^2 T^*M)$$

$$d\omega = 0$$

$$L_X \omega = df$$

$$L_X \omega = 0$$

$$H_{dR}^*(M) \text{ (de Rham)}$$

POISSON

$$\pi \in \mathcal{X}^2(M) = \Gamma(\wedge^2 TM)$$

$$[\pi, \pi] = 0$$

$$X_\pi = \pi(df, \cdot)$$

$$L_{X_\pi} \pi = 0 = [X, \pi]$$

$$H_\pi^*(M) \text{ (Poisson)}$$

Hamiltonian v.f.

Symplectic / Poisson v.f.

Of course, Poisson cohomology has to reduce to de Rham cohomology when the Poisson structure is symplectic

The Jacobi identity for the Schouten bracket is

$$[A, [B, C]] (-1)^{(a-1)(c-1)} + (-1)^{(a-1)(b-1)} [B, [C, A]] + (-1)^{(c-1)(b-1)} [C, [A, B]] = 0$$

$$\text{for } A \in \mathcal{X}^a(M), B \in \mathcal{X}^b(M), C \in \mathcal{X}^c(M).$$

If π is a Poisson tensor, then for any multivector field

Proposition

$$A, [\pi, [\pi, A]] = 0$$

Proof: apply graded Jacobi. ■

For $A \in \mathcal{X}^0(M)$, define $d_\pi(A) = [\pi, A]$.

$$d_\pi^2 = 0 \quad (\text{that's the lemma})$$

Hence we get a complex

$$\cdots \rightarrow \mathcal{X}^{k-1}(M) \xrightarrow{d_\pi} \mathcal{X}^k(M) \xrightarrow{d_\pi} \mathcal{X}^{k+1}(M) \rightarrow \cdots$$

Definition

The Poisson cohomology of (M, π) is

$$H_\pi^k(M) = \frac{\ker(d_\pi: \mathcal{X}^k(M) \rightarrow \mathcal{X}^{k+1}(M))}{\operatorname{Im}(d_\pi: \mathcal{X}^{k-1}(M) \rightarrow \mathcal{X}^k(M))}$$

It's hard to compute!!!

- Mayer-Vietoris
- Künneth is hard.
- can be infinite-dimensional

Example 0

$$\pi = 0 \Rightarrow d_\pi = 0 \Rightarrow H_\pi^k(M) \cong \mathcal{X}^k(M) \quad (\infty\text{-dim.})$$

Example 1

(Lichnerowicz) (M, ω) symplectic $\Rightarrow H_\pi^k(M) = H_{\text{de}}^k(M)$

Why does that work? (M, ω) symplectic \Rightarrow the anchor map $\pi^\#: T^*M \rightarrow TM$ is an isomorphism.

$$\begin{array}{ccccccc} \rightarrow \Omega^{k-1}(M) & \xrightarrow{d} & \Omega^k(M) & \xrightarrow{d} & \Omega^{k+1}(M) & \rightarrow \cdots \\ \pi^\# \downarrow & & \pi^\# \downarrow & & \pi^\# \downarrow & \\ \rightarrow \mathcal{X}^{k-1}(M) & \xrightarrow{d_\pi} & \mathcal{X}^k(M) & \xrightarrow{d_\pi} & \mathcal{X}^{k+1}(M) & \rightarrow \cdots \end{array}$$

Fact: this diagram commutes! 😊

b-symplectic / log-symplectic forms

Example 2

Let (M^{2n}, Π) be an even-dimensional Poisson mfd.

Definition

This is b-Poisson if $\Pi^n \in \Gamma(\Lambda^{2n} TM)$ has graph $p \mapsto \Pi^n(p)$ \pitchfork to the zero section.

Locally, Π looks like $\sum_{i=1}^{n-1} \frac{\partial}{\partial x_i} \wedge \frac{\partial}{\partial y_i} + z \frac{\partial}{\partial z} \wedge \frac{\partial}{\partial t}$

with coordinates $(x_1, y_1, \dots, x_{n-1}, y_{n-1}, z, t)$.

If (M^{2n}, Π) is a compact b-Poisson manifold,

Theorem (Marcut - Osorno, Guillemin - M. - Pires)

$$H_{\Pi}^k(M) \cong H_{dR}^k(M) \oplus H_{dR}^{k-1}(Z)$$

Here $Z \subset M$ is the codimension 1 submanifold defined by $Z = \{p \in M \mid \Pi^n(p) = 0\}$ (it's a submanifold thanks to the transversality hypothesis).

Let \mathfrak{g} be a Lie algebra and let U be an Ad^* -invariant open subset of \mathfrak{g}^* . Then

Example 3

$$H_{\Pi}^*(U) \cong H^*(\mathfrak{g}, C^{\infty}(U))$$

where the \mathfrak{g} -action on $C^{\infty}(U)$ is the coadjoint action (isomorphism at the level of chain complexes)

If \mathfrak{g} is reductive of compact type, then

$$H_{\pi}^*(\mathcal{U}) = H^*(g) \otimes (C^{\infty}(\mathcal{U}))^G$$

by a version of the Whitehead lemma.

LOW-DIMENSIONAL COHOMOLOGY GROUPS

$$H_{\pi}^0(M) = \{f \mid X_f = 0\} = \{f \mid \{f, h\} = 0 \ \forall h \in C^{\infty}(M)\}$$

\Rightarrow CASIMIR FUNCTIONS

$$H_{\pi}^1(M) = \begin{cases} \text{Poisson vector fields} \\ \text{Hamiltonian vector fields} \end{cases} \quad \left(\begin{array}{l} [\pi, X] = L_X \pi \\ -[\pi, f] = X_f \end{array} \right)$$

$$H_{\pi}^2(M) = \frac{\{ \Lambda \mid [\pi, \Lambda] = 0 \}}{\{ \Xi \mid \Xi = [\pi, X] \}} = \mathbb{Z}^2 / B^2$$

$$\text{For } \Lambda \in \mathbb{Z}^2, [\pi + \varepsilon \Lambda, \pi + \varepsilon \Lambda] = \varepsilon^2 [\Lambda, \Lambda] = 0 \text{ mod } \varepsilon^2$$

\rightarrow first order infinitesimal deformation

$\pi + \varepsilon [\pi, X]$ are "trivial" deformations

$$H_{\pi}^2(M) = \frac{\{ \text{first order infinitesimal deformations} \}}{\{ \text{trivial deformations} \}}$$

What we have seen so far:

GEOMETRY

DYNAMICAL OBJECTS

Poisson \longrightarrow constants of motion

Lecture 1

Lecture 2

Singular foliation \longrightarrow symplectic foliation

Poisson map $\longrightarrow \left. \begin{array}{l} \iota: h \longrightarrow g \\ \iota^*: g^* \longrightarrow h^* \end{array} \right\} \text{Thimm's}$

\longrightarrow moment map $\mu: M \longrightarrow g^*$

GEOMETRY

DYNAMICAL OBJECTS

Seite: _____

Poisson cohomology
+

$$[\pi_1, \pi_2] = 0$$

X bi-Hamiltonian

Normal forms

$$X = X_{f_1}^{\pi_1} = X_{f_2}^{\pi_2}$$

$$\Rightarrow \{f_1, f_2\}_1 = \{f_1, f_2\}_2$$



Can we refine these normal forms if we add some extra structure? Constants of motion? Actions?

Lecture 3

6 INTEGRABLE SYSTEMS & NORMAL FORMS

Two Poisson structures π_1, π_2 on M are compatible if $[\pi_1, \pi_2] = 0$ ($\Leftrightarrow \pi_2$ is a cycle in π_1 -Poisson cohomology)

Definition

Moser $L_{X_t} \omega_t = -\alpha$ (ω_t path of symplectic forms)

Remark

The line between two Poisson structures π_1, π_2 , $(1-t)\pi_1 + t\pi_2$, is not in general a Poisson structure. It is so, however, if the two structures are compatible.

\leadsto If π_1, π_2 are compatible Poisson structures, so is $\alpha\pi_1 + \beta\pi_2$ (α, β constants)

Compatible Poisson structures give commuting functions constants of motion.

A v.f. $X \in \mathfrak{X}(M)$ is bi-Hamiltonian with respect to compatible Poisson structures π_1, π_2 if

Definition

$$X = X_{f_1}^{\pi_1} = X_{f_2}^{\pi_2} \quad (f_1, f_2 \in C^\infty(M))$$

Proposition

If $X \in \mathcal{X}(M)$ is bi-hamiltonian with Hamiltonian functions f_1, f_2 , then $\{f_1, f_2\}_{\pi_1} = 0 = \{f_1, f_2\}_{\pi_2}$.

Proof. $0 = \{f_1, f_2\}_{\pi_1} = X_{f_1}^{\pi_1}(f_2) = X_{f_2}^{\pi_2}(f_1) = \{f_2, f_1\}_{\pi_2} = 0$ ■

Cocycles in Poisson cohomology \Rightarrow commuting functions

Definition

An integrable system on a symplectic manifold

(M^{2n}, ω) is given by n functions f_1, \dots, f_n such that

① $df_1 \wedge \dots \wedge df_n \neq 0$ on a dense set;

② $\{f_i, f_j\} = 0 \quad \forall i, j$ (Poisson bracket: $\{f_i, f_j\} = \omega(X_i, X_j)$).

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ACTION-ANGLE COORDINATES FOR INTEGRABLE SYSTEMS ON POISSON MANIFOLDS

CAMILLE LAURENT-GENGOUX, EVA MIRANDA¹, AND POL VANHAECKE²

ABSTRACT. We prove the action-angle theorem in the general, and most natural, context of integrable systems on Poisson manifolds, thereby generalizing the classical proof, which is given in the context of symplectic manifolds. The topological part of the proof parallels the proof of the symplectic case, but the rest of the proof is quite different, since we are naturally led to using the calculus of polyvector fields, rather than differential forms; in particular, we use in the end a Poisson version of the classical Carathéodory-Jacobi-Lie theorem, which we also prove. At the end of the article, we generalize the action-angle theorem to the setting of non-commutative integrable systems on Poisson manifolds.

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1. INTRODUCTION

The action-angle theorem is one of the basic theorems in the theory of integrable systems. In this paper we prove this theorem in the general, and most natural, context of integrable systems on Poisson manifolds.

We recall that a Poisson manifold (M, Π) is a smooth manifold M on which there is given a bivector field Π , with the property that the bracket on $C^\infty(M)$, defined for arbitrary smooth functions f and g on M by

$$\{f, g\} := \Pi(df, dg)$$

is a Lie bracket, i.e., it satisfies the Jacobi identity. On a Poisson manifold (M, Π) , the Hamiltonian operator, which assigns to a function on M a vector field on M , is defined naturally by contracting the bivector field with the function (the “Hamiltonian”): for $h \in C^\infty(M)$ its Hamiltonian vector field is defined by

$$\mathcal{X}_h := \{\cdot, h\} = -\iota_{dh}\Pi. \quad (1.1)$$

Two important consequences of the Jacobi identity for $\{\cdot, \cdot\}$ are that the (generalized distribution) on M , defined by the Hamiltonian vector fields \mathcal{X}_h is integrable, and that the Hamiltonian vector fields which are associated to Poisson commuting functions (usually called functions in involution) are commuting vector fields. The main examples of Poisson manifolds are symplectic manifolds and the dual of a (finite-dimensional) Lie algebra, but there are many other examples, which come up naturally in deformation theory, the theory of R -brackets, Lie-Poisson groups, and so on. Poisson’s original bracket on $C^\infty(\mathbf{R}^{2r})$, given for smooth functions f and g by

$$\{f, g\} := \sum_{i=1}^r \left(\frac{\partial f}{\partial q_i} \frac{\partial g}{\partial p_i} - \frac{\partial g}{\partial q_i} \frac{\partial f}{\partial p_i} \right), \quad (1.2)$$

is still today of fundamental importance in classical and quantum mechanics, and in other areas of mathematical physics. Many examples of integrable Hamiltonian systems are known in the context of Poisson manifolds which are not symplectic. For instance the Kepler problem [20], Toda lattices [1] and the Gelfand-Cetlin systems [11, 10].

One of the main uses of the Poisson bracket is the integration of Hamilton’s equations, which are the equations of motion which describe a classical mechanical system on the phase space $\mathbf{R}^{2r} \simeq T^*\mathbf{R}^r$, defined by a

Hamiltonian h (the energy, viewed as a function on phase space); their solutions are the integral curves of the Hamiltonian vector field \mathcal{X}_h , defined by (1.1) with respect to the Poisson bracket (1.2). The fundamental Liouville theorem states that it suffices to have r independent functions in involution ($f_1 = h, f_2, \dots, f_r$) to quite explicitly (i.e., by quadratures) integrate the equations of motion for generic initial conditions. Moreover, assuming that the so-called invariant manifolds, which are the (generic) submanifolds traced out by the n commuting vector fields \mathcal{X}_{f_i} , are compact, they are (diffeomorphic to) tori $\mathbf{T}^r = \mathbf{R}^r/\Lambda$, where Λ is a lattice in \mathbf{R}^r ; on these tori, which are known as Liouville tori, the flow of each of the vector fields \mathcal{X}_{f_i} is linear, so that the solutions of Hamilton's equations are quasi-periodic. The classical action-angle theorem goes one step further: under the above topological assumption, there exist on a neighbourhood U of every Liouville torus functions $\sigma_1, \dots, \sigma_r$ and \mathbf{R}/\mathbf{Z} -valued functions $\theta_1, \dots, \theta_r$, having the following properties:

- (1) The map Φ , defined by $\Phi := (\theta_1, \dots, \theta_r, \sigma_1, \dots, \sigma_r)$ is a diffeomorphism from U onto the product $\mathbf{T}^r \times B^r$, where B^r is an r -dimensional ball;
- (2) Φ is a canonical map: in terms of $\theta_1, \dots, \theta_r, \sigma_1, \dots, \sigma_r$ the Poisson structure takes the same form as in (1.2) (upon replacing q_i by θ_i and p_i by σ_i);
- (3) Under Φ , the Liouville tori in U correspond to the fibers of the natural projection $\mathbf{T}^r \times B^r \rightarrow B^r$.

The proof of this theorem goes back to Mineur [13, 14, 15]. A proof in the case of a Liouville integrable system on a symplectic manifold was given by Arnold [2]; see also [4, 7, 12]. As established in [11], action-angle coordinates also appear naturally in geometric quantization, for, when an integrable system is interpreted as a polarization, action-angle coordinates determine the so-called Bohr-Sommerfeld leaves: the latter are in particular explicitly described for the Gelfand-Cetlin system in [11].

In the context of Poisson manifolds, the Liouville theorem still holds, up to two adaptations: one needs to take into account the Casimirs (functions whose Hamiltonian vector field are zero) and the singularities of the Poisson structure (the points where the rank of the bivector field drops); for a precise statement and a proof, see [1, Ch. 4.3]. As we show in this paper, the action-angle theorem takes in the case of Poisson manifolds the following form¹

Theorem 1.1. *Let (M, Π) be a Poisson manifold of dimension n and (maximal) rank $2r$. Suppose that $\mathbf{F} = (f_1, \dots, f_s)$ is an integrable system on (M, Π) , i.e., $r + s = n$ and the components of \mathbf{F} are independent and in involution. Suppose that $m \in M$ is a point such that*

- (1) $d_m f_1 \wedge \dots \wedge d_m f_s \neq 0$;

¹An equivalent statement, without proof, was given in [1, Ch. 4.3].

- (2) *The rank of Π at m is $2r$;*
- (3) *The integral manifold \mathcal{F}_m of $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$, passing through m , is compact.*

Then there exists \mathbf{R} -valued smooth functions $(\sigma_1, \dots, \sigma_s)$ and \mathbf{R}/\mathbf{Z} -valued smooth functions $(\theta_1, \dots, \theta_r)$, defined in a neighborhood U of \mathcal{F}_m such that

- (1) *The functions $(\theta_1, \dots, \theta_r, \sigma_1, \dots, \sigma_s)$ define an isomorphism $U \simeq \mathbf{T}^r \times B^s$;*
- (2) *The Poisson structure can be written in terms of these coordinates as*

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial \theta_i} \wedge \frac{\partial}{\partial \sigma_i},$$

in particular the functions $\sigma_{r+1}, \dots, \sigma_s$ are Casimirs of Π (restricted to U);

- (3) *The leaves of the surjective submersion $\mathbf{F} = (f_1, \dots, f_s)$ are given by the projection onto the second component $\mathbf{T}^r \times B^s$, in particular, the functions $\sigma_1, \dots, \sigma_s$ depend on the functions f_1, \dots, f_s only.*

The functions $\theta_1, \dots, \theta_r$ are called angle coordinates, the functions $\sigma_1, \dots, \sigma_r$ are called action coordinates and the remaining functions $\sigma_{r+1}, \dots, \sigma_s$ are called transverse coordinates.

Our proof of theorem 1.1, consists of several conceptually different steps, which are in 1-1 correspondence with the (a) topological, (b) group theoretical, (c) geometrical and (d) analytical aspects of the construction of the coordinates. It parallels Duistermaat's proof, which deals with the symplectic case [7]; while (a) and (b) are direct generalizations of his proof, (c) and (d) are however not.

(a) The topological part of the proof amounts to showing that in the neighborhood of the invariant manifold \mathcal{F}_m , we have locally trivial torus fibration (Paragraph 3.2). Once we have shown that the compact invariant manifolds are the connected components of the fibers of a submersive map (the map \mathbf{F} , restricted to some open subset), the proof of this part is similar as in the symplectic case.

(b) The (commuting) Hamiltonian vector fields are tangent to the tori of this fibration; integrating them we get an induced torus action (action by \mathbf{T}^r) on each of these tori, but in general these actions cannot be combined into a single torus action. Taking appropriate linear combinations of the vector fields, using \mathbf{F} -basic functions as coefficients, by a procedure called "uniformization of the periods", one constructs new vector fields Y_1, \dots, Y_r which are tangent to the fibration, and which now integrate into a single torus action. This is the content of step 1 in the proof of proposition 3.6. This step, which is an application of the implicit function theorem, is identical as in the symplectic case.

(c) The newly constructed vector fields Y_i are the fundamental vector fields of a torus action. We first show that they are Poisson vector fields, i.e., that they preserve the Poisson structure (step 2 in the proof of proposition 3.6). The key (and non-trivial) point of the proof is the periodicity of the vector fields Y_i . We then prove (in step 3 of the proposition) the stronger statement that these vector fields are Hamiltonian vector fields, at least locally, by constructing quite explicitly their Hamiltonians, which will in the end play the role of action coordinates.

(d) In the last step (theorem 3.8), we use the Carathéodory-Jacobi-Lie theorem for Poisson manifolds to construct on the one hand coordinates which are conjugate to the action coordinates (angle coordinates and transverse coordinates) and on the other hand to extend these coordinates to a neighborhood of the Liouville torus \mathcal{F}_m . The Carathéodory-Jacobi-Lie theorem for Poisson manifolds, to which Section 2 is entirely devoted, provides a set of canonical local coordinates for a Poisson structure Π , containing a given set p_1, \dots, p_r of functions in involution. It generalizes both the classical Carathéodory-Jacobi-Lie theorem for symplectic manifolds [12, Th. 13.4.1] and Weinstein's splitting theorem [19, Th. 2.1]. We are convinced that this theorem, which is new, has other interesting applications, as in the study of local forms and stability of integrable systems.

The action-angle theorem has been proven by [17] in the general context of non-commutative integrable systems on a symplectic manifold (see the Appendix for a comparison between this notion and some closely related notions of integrability). Roughly speaking, a non-commutative integrable system has more constants of motion than a Liouville integrable system, accounting for linear motion on smaller tori, but not all these functions are in involution. This notion has a natural definition in the case of Poisson manifolds, proposed here (definition 4.1); it generalizes both the notion of Liouville integrability on a Poisson manifold and the notion of non-commutative integrability on a symplectic manifold. We show in Section 4 that our proof can be adapted (i.e., generalized) to provide a proof of the action-angle theorem in this very general context.

The structure of the paper is as follows. We state and prove the Carathéodory-Jacobi-Lie theorem for Poisson manifolds in Paragraph 2.1 and we give in Paragraph 2.2 a counterexample which shows that a mild generalization of the latter theorem does not hold in general. The action-angle theorem for Liouville integrable systems on Poisson manifolds is given in Section 3. We show in Section 4 how this theorem can be adapted to the more general case of non-commutative integrable systems on Poisson manifolds. The appendix to the paper is devoted to the geometrical formulation of the notion of a non-commutative integrable system on a Poisson manifold.

In this paper, all manifolds and objects considered on them are smooth and we write $\{f, g\}$ for $\Pi(df, dg)$.

2. THE CARATHÉODORY-JACOBI-LIE THEOREM FOR POISSON MANIFOLDS

In this section we prove a natural generalization of the classical Carathéodory-Jacobi-Lie theorem [12, Th. 13.4.1] for an arbitrary Poisson manifold (M, Π) . It provides a set of canonical local coordinates for the Poisson structure Π , which contains a given set p_1, \dots, p_r of functions in involution (i.e., functions which pairwise commute for the Poisson bracket), whose Hamiltonian vector fields are assumed to be independent at a point $m \in M$ (theorem 2.1). This result, which is interesting in its own right, will be used in our proof of the action-angle theorem. We show in Paragraph 2.2 by giving a counterexample that canonical coordinates containing a given set of functions in involution may fail to exist as soon as the Hamiltonian vector fields $\mathcal{X}_{p_1}, \dots, \mathcal{X}_{p_r}$ are dependent at m , even if they are independent at all other points in a neighborhood of m .

2.1. The theorem. The main result of this section is the following theorem.

Theorem 2.1. *Let m be a point of a Poisson manifold (M, Π) of dimension n . Let p_1, \dots, p_r be r functions in involution, defined on a neighborhood of m , which vanish at m and whose Hamiltonian vector fields are linearly independent at m . There exist, on a neighborhood U of m , functions $q_1, \dots, q_r, z_1, \dots, z_{n-2r}$, such that*

- (1) *The n functions $(p_1, q_1, \dots, p_r, q_r, z_1, \dots, z_{n-2r})$ form a system of coordinates on U , centered at m ;*
- (2) *The Poisson structure Π is given on U by*

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial q_i} \wedge \frac{\partial}{\partial p_i} + \sum_{i,j=1}^{n-2r} g_{ij}(z) \frac{\partial}{\partial z_i} \wedge \frac{\partial}{\partial z_j}, \quad (2.1)$$

where each function $g_{ij}(z)$ is a smooth function on U and is independent of $p_1, \dots, p_r, q_1, \dots, q_r$.

The rank of Π at m is $2r$ if and only if all the functions $g_{ij}(z)$ vanish for $z = 0$.

Proof. We show the first part of the theorem by induction on r . For $r = 0$, every system of coordinates z_1, \dots, z_n , centered at m , does the job. Assume that the result holds true for every point in every Poisson manifold and every $(r - 1)$ -tuple of functions as above, with $r \geq 1$. We prove it for r . To do this, we consider an arbitrary point m in an n -dimensional Poisson manifold (M, Π) , and we assume that we are given functions in involution p_1, \dots, p_r , defined on a neighborhood of m , which vanish at m , and whose Hamiltonian vector fields are linearly independent at m . On a neighbourhood of m , the distribution $\mathcal{D} := \langle \mathcal{X}_{p_1}, \dots, \mathcal{X}_{p_r} \rangle$ has constant rank r and is an involutive distribution because $[\mathcal{X}_{p_i}, \mathcal{X}_{p_j}] = -\mathcal{X}_{\{p_i, p_j\}} = 0$. By the Frobenius theorem, there exist local coordinates g_1, \dots, g_n , centered at m , such that $\mathcal{X}_{p_i} = \frac{\partial}{\partial g_i}$

for $i = 1, \dots, r$, on a neighbourhood of m . Setting $q_r := g_r$ we have

$$\mathcal{X}_{q_r}[p_i] = -\mathcal{X}_{p_i}[q_r] = -\delta_{i,r}, \quad i = 1, \dots, r, \quad (2.2)$$

in particular (1) the $r + 1$ vectors $d_m p_1, \dots, d_m p_r$ and $d_m q_r$ of $T_m^* M$ are linearly independent, and (2) the vector fields \mathcal{X}_{q_r} and \mathcal{X}_{p_r} are independent at m . It follows that a distribution \mathcal{D}' (of rank 2) is defined by \mathcal{X}_{q_r} and \mathcal{X}_{p_r} . It is an integrable distribution because $[\mathcal{X}_{q_r}, \mathcal{X}_{p_r}] = -\mathcal{X}_{\{q_r, p_r\}} = 0$. Applied to \mathcal{D}' , the Frobenius theorem yields the existence of local coordinates v_1, \dots, v_n , centered at m , such that

$$\mathcal{X}_{p_r} = \frac{\partial}{\partial v_{n-1}} \quad \text{and} \quad \mathcal{X}_{q_r} = \frac{\partial}{\partial v_n}. \quad (2.3)$$

Since the differentials $d_m v_1, \dots, d_m v_{n-2}$ vanish on $\mathcal{X}_{p_r}(m)$ and on $\mathcal{X}_{q_r}(m)$, it follows that $(d_m v_1, \dots, d_m v_{n-2}, d_m p_r, d_m q_r)$ is a basis of $T_m^* M$. Therefore, the n functions $(v_1, \dots, v_{n-2}, p_r, q_r)$ form a system of local coordinates, centered at m . It follows from (2.3) that the Poisson structure takes in terms of these coordinates the following form:

$$\Pi = \frac{\partial}{\partial q_r} \wedge \frac{\partial}{\partial p_r} + \sum_{i,j=1}^{n-2} h_{ij}(v_1, \dots, v_{n-2}, p_r, q_r) \frac{\partial}{\partial v_i} \wedge \frac{\partial}{\partial v_j}.$$

The Jacobi identity, applied to the triplets (p_r, v_i, v_j) and (q_r, v_i, v_j) , implies that the functions h_{ij} do not depend on the variables p_r, q_r , so that

$$\Pi = \frac{\partial}{\partial q_r} \wedge \frac{\partial}{\partial p_r} + \sum_{i,j=1}^{n-2} h_{ij}(v_1, \dots, v_{n-2}) \frac{\partial}{\partial v_i} \wedge \frac{\partial}{\partial v_j}, \quad (2.4)$$

which means that Π is, in a neighborhood of m , the product of a symplectic structure (on a neighborhood of the origin in \mathbf{R}^2) and a Poisson structure (on a neighborhood of the origin in \mathbf{R}^{n-2}). In order to apply the recursion hypothesis, we need to show in case $r - 1 > 0$ that p_1, \dots, p_{r-1} depend only on the coordinates v_1, \dots, v_{n-2} , i.e., are independent of p_r and q_r ,

$$\frac{\partial p_i}{\partial p_r} = 0 = \frac{\partial p_i}{\partial q_r} \quad i = 1, \dots, r - 1. \quad (2.5)$$

Both equalities in (2.5) follow from the fact that p_i is in involution with p_r and q_r , for $i = 1, \dots, r - 1$, combined with (2.4):

$$0 = \{p_i, p_r\} = \frac{\partial p_i}{\partial q_r}, \quad 0 = \{p_i, q_r\} = -\frac{\partial p_i}{\partial p_r}.$$

We may now apply the recursion hypothesis on the second term in (2.4), together with the functions p_1, \dots, p_{r-1} . It leads to a system of local coordinates $(p_1, q_1, \dots, p_r, q_r, z_1, \dots, z_{n-2r})$ in which Π is given by (2.1). This shows the first part of the theorem. The second part of the theorem is an easy consequence of (2.1), since it implies that the rank of Π at m is $2r$ plus the rank of the second term in the right hand side of (2.1), at $z = 0$. \square

Remark 2.2. The classical Carathéodory-Jacobi-Lie theorem corresponds to the case $\dim M = 2r$. Then Π is the Poisson structure associated to a symplectic structure, in the neighborhood of m . Theorem 2.1 then says that Π can be written in the simple form

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial q_i} \wedge \frac{\partial}{\partial p_i}, \quad (2.6)$$

where we recall that the (involutive) set of functions p_1, \dots, p_r is prescribed.

Remark 2.3. Theorem 2.1 and their proof, as they are stated, do not yield the existence of the involutive set of functions p_1, \dots, p_r , a fact which is plain in Weinstein's splitting theorem. However, if we forget in our proof that these functions are prescribed, we can easily adapt the induction hypotheses, adding the existence of r such functions, when the rank of the Poisson structure at m is at least $2r$. In this sense, our theorem is an amplification of Weinstein's splitting theorem.

Remark 2.4. Theorem 2.1 holds true for holomorphic Poisson manifolds; the local coordinates are in this case holomorphic coordinates and the functions $g_{ij}(z)$ are holomorphic functions, independent from $p_1, \dots, p_r, q_1, \dots, q_r$. Up to these substitutions, the given proof is valid word by word.

2.2. A counterexample. If we denote in theorem 2.1 the rank of Π at m by $2r'$, then $2r' \geq 2r$, because the involutive set of functions p_1, \dots, p_r define a totally isotropic foliation in a neighborhood of m . It means that, if $2r' < 2r$ and one is given independent functions in involution p_1, \dots, p_r , then their Hamiltonian vector fields $\mathcal{X}_{p_1}, \dots, \mathcal{X}_{p_r}$ are *dependent* at m . In the extremal case in which $\dim \langle \mathcal{X}_{p_1}(m), \dots, \mathcal{X}_{p_r}(m) \rangle = r'$ one has², according to theorem 2.1, that there exist functions $q_1, \dots, q_{r'}$ and $z_1, \dots, z_{n-2r'}$ such that Π takes the form

$$\Pi = \sum_{i=1}^{r'} \frac{\partial}{\partial q_i} \wedge \frac{\partial}{\partial p_i} + \sum_{k,l=1}^{n-2r'} \phi_{k,l}(z_1, \dots, z_{n-2r'}) \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_l}.$$

A natural question is whether $r - r'$ of the functions z_i can be chosen as $p_{r'+1}, \dots, p_r$, or, more generally, as functions which depend only on p_1, \dots, p_r . We show in the following (counter) example that this is not possible, in general.

Example 2.5. On \mathbf{R}^4 , with coordinates f_1, f_2, g_1, g_2 , consider the bivector field, given by

$$\Pi = \frac{\partial}{\partial g_1} \wedge \frac{\partial}{\partial f_1} + \chi(g_2) \frac{\partial}{\partial g_2} \wedge \frac{\partial}{\partial f_2} + \psi(g_2) \frac{\partial}{\partial g_1} \wedge \frac{\partial}{\partial f_2}, \quad (2.7)$$

where $\chi(g_2)$ and $\psi(g_2)$ are smooth functions that depend only on g_2 , and which vanish for $g_2 = 0$, so that the rank of Π at the origin is 2. A direct

²Possibly up to a relabelling of the p_i , so that $\dim \langle \mathcal{X}_{p_1}(m), \dots, \mathcal{X}_{p_{r'}}(m) \rangle = r'$.

computation shows that this bivector field is a Poisson bivector field and that f_1 and f_2 are in involution. We show that for some choice of χ and ψ there exists no system of coordinates p_1, q_1, z_1, z_2 , centered at 0, with p_1, z_1 depending only on f_1 and f_2 , such that

$$\Pi = \frac{\partial}{\partial q_1} \wedge \frac{\partial}{\partial p_1} + \phi(z_1, z_2) \frac{\partial}{\partial z_1} \wedge \frac{\partial}{\partial z_2}. \quad (2.8)$$

To do this, let us assume that such a system of coordinates exists. Taking the Poisson bracket of $p_1 = p_1(f_1, f_2)$ and $z_1 = z_1(f_1, f_2)$ with q_1 yields, in view of (2.8),

$$\begin{aligned} 1 &= \{q_1, p_1\} = \frac{\partial p_1}{\partial f_1} \{q_1, f_1\} + \frac{\partial p_1}{\partial f_2} \{q_1, f_2\}, \\ 0 &= \{q_1, z_1\} = \frac{\partial z_1}{\partial f_1} \{q_1, f_1\} + \frac{\partial z_1}{\partial f_2} \{q_1, f_2\}. \end{aligned} \quad (2.9)$$

Let N denote the locus defined by $f_1 = f_2 = 0$, which is a smooth surface in a neighborhood of the origin. Let q denote the restriction of q_1 to N . Since \mathcal{X}_{f_1} and \mathcal{X}_{f_2} are tangent to N , $\mathcal{X}_{f_i}[q] = \{q_1, f_i\}|_N$, so that (2.9), restricted to N , becomes

$$\begin{aligned} 1 &= \lambda_1 \mathcal{X}_{f_1}[q] + \lambda_2 \mathcal{X}_{f_2}[q], \\ 0 &= \lambda_3 \mathcal{X}_{f_1}[q] + \lambda_4 \mathcal{X}_{f_2}[q], \end{aligned} \quad (2.10)$$

where $\lambda_1, \dots, \lambda_4$ are constants (because p_1, z_1 depend only on f_1, f_2), and satisfy $\lambda_1 \lambda_4 - \lambda_2 \lambda_3 \neq 0$, since p_1 and z_1 are part of a coordinate system centered at the origin. It follows that

$$\mathcal{X}_{f_1}[q] = c_1 \text{ and } \mathcal{X}_{f_2}[q] = c_2, \quad (2.11)$$

where c_1 and c_2 are constants, which cannot be both equal to zero, in view of (2.10). Writing \mathcal{X}_{f_1} and \mathcal{X}_{f_2} in terms of the original variables, using (2.7), we find that $q = q(g_1, g_2)$ must satisfy

$$\frac{\partial q}{\partial g_1} = c_1, \quad \chi(g_2) \frac{\partial q}{\partial g_2} + \psi(g_2) \frac{\partial q}{\partial g_1} = c_2.$$

Evaluating the second equation at $g_1 = g_2 = 0$ gives $c_2 = 0$, hence $c_1 \neq 0$ and $q(g_1, g_2) = c_1 g_1 + r(g_2)$ for some smooth function $r(g_2)$. Then the second condition leads to the following differential equation for r ,

$$\chi(g_2) r'(g_2) = -\psi(g_2) c_1. \quad (2.12)$$

But this equation does not admit a smooth solution, unless $\psi(g_2)/\chi(g_2)$ admits a smooth continuation at 0. If, for example, $\psi(g_2) = g_2$ and $\chi(g_2) = g_2^2$, then there is no solution $r(g_2)$ to (2.12), which is smooth in the neighborhood of 0, hence a system of coordinates in which Π takes the form (2.8) does not exist.

3. ACTION-ANGLE COORDINATES FOR LIOUVILLE INTEGRABLE SYSTEMS ON POISSON MANIFOLDS

In this section we prove the existence of action-angle coordinates in the neighborhood of every standard Liouville torus of an integrable system on an arbitrary Poisson manifold.

3.1. Standard Liouville tori of Liouville integrable systems. We first recall the definition of a Liouville integrable system on a Poisson manifold.

Definition 3.1. Let (M, Π) be a Poisson manifold of (maximal) rank $2r$ and of dimension n . An s -tuple of functions $\mathbf{F} = (f_1, \dots, f_s)$ on M is said to define a *Liouville integrable system* on (M, Π) if

- (1) f_1, \dots, f_s are independent (i.e., their differentials are independent on a dense open subset of M);
- (2) f_1, \dots, f_s are in involution (pairwise);
- (3) $r + s = n$.

Viewed as a map, $\mathbf{F} : M \rightarrow \mathbf{R}^s$ is called the *momentum map* of (M, Π, \mathbf{F}) .

We denote by M_r the open subset of M where the rank of Π is equal to $2r$; points of M_r are called *regular points* of M . We denote by $\mathcal{U}_{\mathbf{F}}$ the dense open subset of M , which consists of all points of M where the differentials of the elements of \mathbf{F} are linearly independent,

$$\mathcal{U}_{\mathbf{F}} := \{m \in M \mid d_m f_1 \wedge d_m f_2 \wedge \dots \wedge d_m f_s \neq 0\}. \quad (3.1)$$

On the non-empty open subset $M_r \cap \mathcal{U}_{\mathbf{F}}$ of M the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$ define a distribution \mathcal{D} of rank r , since at each point m of M_r the kernel of Π_m has dimension $n - 2r = s - r$. The distribution \mathcal{D} is integrable because the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$ pairwise commute,

$$[\mathcal{X}_{f_i}, \mathcal{X}_{f_j}] = -\mathcal{X}_{\{f_i, f_j\}} = 0,$$

for $1 \leq i < j \leq s$. The integral manifolds of \mathcal{D} are the leaves of a regular foliation, which we denote by \mathcal{F} ; the leaf of \mathcal{F} , passing through m , is denoted by \mathcal{F}_m , and is called the *invariant manifold* of \mathbf{F} , through m . For what follows, we will be uniquely interested in the case in which \mathcal{F}_m is compact. According to the classical Liouville theorem, adapted to the case of Poisson manifolds (see [1, Sect. 4.3] for a proof in the Poisson manifold case), every compact invariant manifold \mathcal{F}_m is diffeomorphic to the torus $\mathbf{T}^r := (\mathbf{R}/\mathbf{Z})^r$; more precisely, the diffeomorphism can be chosen such that each of the vector fields \mathcal{X}_{f_i} is sent to a constant (i.e., translation invariant) vector field on \mathbf{T}^r . Such a torus is called a *standard Liouville torus*.

3.2. Foliation by standard Liouville tori. As a first step in establishing the existence of action-angle coordinates, we prove that, in some neighborhood of a standard Liouville torus, the invariant manifolds of an integrable system (M, Π, \mathbf{F}) form a trivial torus fibration.

Proposition 3.2. *Suppose that \mathcal{F}_m is a standard Liouville torus of an integrable system (M, Π, \mathbf{F}) of dimension $n := \dim M$ and rank $2r := Rk \Pi$. There exists an open subset $U \subset M_r \cap \mathcal{U}_{\mathbf{F}}$, containing \mathcal{F}_m , and there exists a diffeomorphism $\phi : U \simeq \mathbf{T}^r \times B^{n-r}$, which takes the foliation \mathcal{F} to the foliation, defined by the fibers of the canonical projection $p_B : \mathbf{T}^r \times B^{n-r} \rightarrow B^{n-r}$, leading to the following commutative diagram.*

$$\begin{array}{ccc} \mathcal{F}_m & \hookrightarrow & U \xrightarrow[\simeq]{\phi} \mathbf{T}^r \times B^{n-r} \\ & & \downarrow \mathbf{F}|_U \quad \swarrow p_B \\ & & B^{n-r} \end{array}$$

Proof. We first show that the foliation \mathcal{F} , which consists of the maximal integral manifolds of the foliation \mathcal{D} , defined by the integrable vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$, where $s := n - r$, coincides with the foliation $\bar{\mathcal{F}}$, defined by the fibers of the submersion

$$\bar{\mathbf{F}} = (f_1, \dots, f_s) : M_r \cap \mathcal{U}_{\mathbf{F}} \rightarrow \mathbf{R}^s,$$

which is the restriction of $\mathbf{F} : M \rightarrow \mathbf{R}^s$ to $M_r \cap \mathcal{U}_{\mathbf{F}}$. Since all leaves of $\bar{\mathcal{F}}$ and of \mathcal{F} are r -dimensional, it suffices to show that the two leaves, which pass through an arbitrary point $m \in M_r \cap \mathcal{U}_{\mathbf{F}}$, have the same tangent space at m . Since f_1, \dots, f_s are pairwise in involution, each of the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$ is tangent to the fibers of $\bar{\mathbf{F}}$, i.e., to the leaves of $\bar{\mathcal{F}}$. Thus, $T_m \mathcal{F} \subset T_m \bar{\mathcal{F}}$, which implies that both tangent spaces are equal, since they have the same dimension r .

Suppose now that \mathcal{F}_m is a standard Liouville torus. We show that there exists a neighborhood U of \mathcal{F}_m and a diffeomorphism $\phi : U \rightarrow \mathcal{F}_m \times B^s$, which sends the foliation $\bar{\mathcal{F}}$ ($= \mathcal{F}$), restricted to U , to the foliation defined by p_B on $\mathcal{F}_m \times B^s$. The proof of this fact depends only on the fact that \mathcal{F}_m is a compact component of a fiber of a submersion (namely $\bar{\mathbf{F}}$). Notice that since $\bar{\mathbf{F}}$ is a submersion, every point $m' \in \bar{\mathcal{F}}_m = \mathcal{F}_m$ has a neighborhood $U_{m'}$ in M , which is diffeomorphic to the product of a neighborhood $V_{m'}$ of m' in \mathcal{F}_m times an open ball $B_{m'}^s$, centered at $\bar{\mathbf{F}}(m') = \bar{\mathbf{F}}(m)$ in \mathbf{R}^s ; such a diffeomorphism $\phi_{m'}$, as provided by the implicit function theorem, is a lifting of $\bar{\mathbf{F}}$, i.e., it leads to the following commutative diagram:

$$\begin{array}{ccc} U_{m'} & \xrightarrow{\phi_{m'}} & V_{m'} \times B_{m'}^s \\ & \searrow \bar{\mathbf{F}} & \downarrow p_B \\ & & B_{m'}^s \end{array}$$

Since \mathcal{F}_m is compact, it is covered by finitely many of the sets $V_{m'}$, say $V_{m_1}, \dots, V_{m_\ell}$. Thus, if every pair of the diffeomorphisms $\phi_{m_1}, \dots, \phi_{m_\ell}$ agrees on the intersection of their domain of definition (whenever non-empty), we

can define a global diffeomorphism on a neighborhood U of \mathcal{F}_m , whose image is the intersection of the concentric balls $B_{m_1}^s, \dots, B_{m_\ell}^s$. In order to ensure that these diffeomorphisms agree, we need to choose them in a more specific way. This is done by choosing an arbitrary Riemannian metric on M . Using the exponential map, defined by the metric, we can identify a neighborhood of the zero section in the normal bundle of \mathcal{F}_m , with a neighborhood of \mathcal{F}_m in M ; in particular, for every $m' \in \mathcal{F}_m$ there exist neighborhoods $U_{m'}$ of m' in M and $V_{m'}$ of m' in \mathcal{F}_m , with smooth maps $\psi_{m'} : U_{m'} \rightarrow V_{m'}$, which have the important virtue that they agree on the intersection of their domains. Upon shrinking the open subsets $U_{m'}$, if necessary, the maps $\phi_{m'} := \psi_{m'} \times (f_1, \dots, f_s)$ are a choice of diffeomorphisms, defined on a neighborhood U of \mathcal{F}_m , with the required properties. \square

Corollary 3.3. *Suppose that \mathcal{F}_m is a standard Liouville torus of an integrable system (M, Π, \mathbf{F}) of dimension $n := \dim M$ and rank $2r := \text{Rk } \Pi$. There exists an open subset $U \subset M_r \cap \mathcal{U}_{\mathbf{F}}$, containing \mathcal{F}_m , and there exist $n - 2r$ functions z_1, \dots, z_{n-2r} on U which are Casimir functions of Π , and whose differentials are independent at every point of U .*

Proof. Let $U \subset M_r \cap \mathcal{U}_{\mathbf{F}}$ and ϕ be as given by proposition 3.2. We consider, besides \mathcal{D} , another integrable distribution on U : the distribution \mathcal{D}' defined by all Hamiltonian vector fields on U ; it has rank $2r$ and its leaves are the symplectic leaves of (U, Π) . Since \mathcal{D} is the distribution, defined by the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$, we have that $\mathcal{D} \subset \mathcal{D}'$. Consider the submersive map $p_B \circ \phi : U \rightarrow \mathbf{T}^r \times B^s \rightarrow B^s$, whose fibers are by assumption the leaves of \mathcal{F} , i.e., the integral manifolds of \mathcal{D} (restricted to U), so that the kernel of $d(p_B \circ \phi)$ is precisely \mathcal{D} . The image of \mathcal{D}' by $d(p_B \circ \phi)$ is therefore a (smooth) distribution \mathcal{D}'' of rank r on B^s , which is integrable, since \mathcal{D}' is integrable. The foliation defined by the integral manifolds of \mathcal{D}'' is, in the neighborhood of the point $p_B(\phi(m))$, defined by $s - r = n - 2r$ independent functions z'_1, \dots, z'_{n-2r} . Pulling them back to M , we get functions z_1, \dots, z_{n-2r} on a neighborhood U of \mathcal{F}_m , with independent differentials on U , and they are Casimir functions because they are constant on the leaves of \mathcal{D}' , which are the symplectic leaves of (U, Π) . \square

For Liouville tori in an integrable system, which are not standard, there may not exist a neighborhood on which the invariant manifolds of the integrable system are locally trivial. We show this in the following example.

Example 3.4. Let M be the product of a Möbius band with an interval, which is obtained by identifying on $M_0 := [-1, 1] \times]-1, 1[\times \mathbf{R}$ in pairs the points $(-1, y, z)$ and $(1, -y, z)$, where y and z are arbitrary. On M_0 , consider the vector field $\mathcal{V}_0 := \partial/\partial x$, the Poisson structure

$$\Pi_0 := \frac{\partial}{\partial x} \wedge \frac{\partial}{\partial z},$$

and the function $F := z$. The algebra of Casimir functions of Π_0 consists of all smooth functions on M_0 that are independent of x and z (i.e., arbitrary smooth functions in y). Clearly, both \mathcal{V}_0 and Π_0 and z go down to M , yielding a vector field \mathcal{V} , a Poisson structure $\Pi = \mathcal{V} \wedge \partial/\partial z$ and a function z on M . What does *not* go down to M is the function y . In fact, only even functions in y go down and the algebra of Casimir functions of Π is the algebra of even functions in y , viewed as functions on M . This remains true if we restrict M to any neighborhood of the central circle $y = z = 0$, which is a leaf of the foliation, defined by the fibers of F . Since the differential of an even function in y vanishes at all points where $y = 0$, the central circle is not a standard Liouville torus. Since every neighborhood of the central circle contains leaves that spin around the Möbius band twice, the Liouville tori do not form a locally trivial torus fibration in the neighborhood of the central circle.

3.3. Standard Liouville tori and Hamiltonian actions. According to proposition 3.2, the study of an integrable system (M, Π, \mathbf{F}) in the neighborhood of a standard Liouville torus amounts to the study of an integrable system $(\mathbf{T}^r \times B^{n-r}, \Pi_0, p_B)$, where Π_0 is a Poisson structure on $\mathbf{T}^r \times B^{n-r}$ of constant rank $2r$ and the map $p_B : \mathbf{T}^r \times B^{n-r} \rightarrow B^{n-r}$ is the projection on the second factor. We write the latter integrable system in the sequel as $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ and we denote the components of \mathbf{F} by $\mathbf{F} = (f_1, \dots, f_s)$ where $s := n - r$, as before. We show in the following lemma that we may assume that the first r vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent on $\mathbf{T}^r \times B^s$, hence span the fibers of \mathbf{F} at each point.

Lemma 3.5. *Let $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ be an integrable system, where Π has constant rank $2r$ and $\mathbf{F} : \mathbf{T}^r \times B^s \rightarrow B^s$ denotes the projection on the second component. Let $m \in \mathbf{T}^r \times \{0\}$ and suppose that the components of $\mathbf{F} = (f_1, \dots, f_s)$ are ordered such that the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at m . There exists a ball $B_0^s \subset B^s$, centered at 0, such that $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent on $\mathbf{T}^r \times B_0^s$.*

Proof. We denote by $\mathcal{L}_{\mathcal{V}}$ the Lie derivative with respect to a vector field \mathcal{V} . Since the vector fields \mathcal{X}_{f_i} pairwise commute,

$$\mathcal{L}_{\mathcal{X}_{f_j}}(\mathcal{X}_{f_1} \wedge \dots \wedge \mathcal{X}_{f_r}) = \sum_{i=1}^r \mathcal{X}_{f_1} \wedge \dots \wedge [\mathcal{X}_{f_j}, \mathcal{X}_{f_i}] \wedge \dots \wedge \mathcal{X}_{f_r} = 0,$$

for $j = 1, \dots, s$. It means that $\mathcal{X}_{f_1} \wedge \dots \wedge \mathcal{X}_{f_r}$ is conserved by the flow of each one of the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_s}$. In particular, if this r -vector field is non-vanishing at $m \in \mathbf{T}^r \times \{0\}$ then it is non-vanishing on the entire integral manifold through m of the distribution \mathcal{D} , defined by these vector fields. Since this integral manifold, which is a torus, is compact, it is actually non-vanishing on a neighborhood of the integral manifold, which we can choose of the form $\mathbf{T}^r \times B_0^s$, where $B_0^s \subset B^s$ is a ball, centered at 0. \square

Given an integrable system $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$, where Π has constant rank and $\mathbf{F} = (f_1, \dots, f_s)$ is the projection on the second component, the Hamiltonian vector fields \mathcal{X}_{f_i} need not be constant on the fibers of \mathbf{F} (which are tori), and even if they are, they may vary from one fiber to another in the sense that they do not come from the single action of the torus \mathbf{T}^r on $\mathbf{T}^r \times B^s$. We show in the following proposition how this can be achieved, upon replacing the Hamiltonian vector fields \mathcal{X}_{f_i} by well-chosen linear combinations, with as coefficients \mathbf{F} -basic functions, i.e., functions of the form $\mathbf{F} \circ \lambda$, where $\lambda \in C^\infty(B^s)$; equivalently, smooth functions on $\mathbf{T}^r \times B^s$ which are constant on the fibers of \mathbf{F} .

Proposition 3.6. *Let $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ be an integrable system, where Π has constant rank $2r$ and $\mathbf{F} = (f_1, \dots, f_s)$ is projection on the second component. Suppose that the r vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at all points of $\mathbf{T}^r \times B^s$. There exists a ball $B_0^s \subset B^s$, also centered at 0, and there exist \mathbf{F} -basic functions $\lambda_i^j \in C^\infty(B_0^s)$, such that the r vector fields $\mathcal{Y}_i := \sum_{j=1}^r \lambda_i^j \mathcal{X}_{f_j}$, ($i = 1, \dots, r$), are the fundamental vector fields of a Hamiltonian torus action of \mathbf{T}^r on $\mathbf{T}^r \times B_0^s$.*

The proof uses the following lemma.

Lemma 3.7. *Let \mathcal{Y} be a Poisson vector field on a Poisson manifold (M, Π) of dimension n and rank $2r$. If \mathcal{Y} is tangent to all symplectic leaves of M , then \mathcal{Y} is Hamiltonian in the neighborhood of every point $m \in M$ where the rank of Π is $2r$.*

Proof. If the rank of Π at m is $2r$, so that m is a regular point of Π , then there exists local coordinates $(p_1, q_1, \dots, p_r, q_r, z_1, \dots, z_{n-2r})$ in a neighborhood U of m with respect to which the Poisson structure P is given by:

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial q_i} \wedge \frac{\partial}{\partial p_i}.$$

The vector fields $\frac{\partial}{\partial q_1}, \frac{\partial}{\partial p_1}, \dots, \frac{\partial}{\partial q_r}, \frac{\partial}{\partial p_r}$ span the symplectic leaves of Π on U . Therefore, every vector field \mathcal{Y} , which is tangent to the symplectic leaves of Π , is of the form

$$\mathcal{Y} = \sum_{i=1}^r a_i \frac{\partial}{\partial p_i} + \sum_{i=1}^r b_i \frac{\partial}{\partial q_i}$$

for some smooth functions $a_1, \dots, a_r, b_1, \dots, b_r$, defined on U . The relation $[\mathcal{Y}, \Pi] = 0$ imposes the following set of equations to be satisfied for all $i, j = 1, \dots, r$:

$$\frac{\partial a_i}{\partial q_j} = \frac{\partial a_j}{\partial q_i}, \frac{\partial b_i}{\partial p_j} = \frac{\partial b_j}{\partial p_i} \text{ and } \frac{\partial a_i}{\partial p_j} = -\frac{\partial b_i}{\partial q_j}$$

By the classical Poincaré lemma, there exists a function h , defined on U , which satisfies, for $i = 1, \dots, r$:

$$a_i = -\frac{\partial h}{\partial q_i} \text{ and } b_i = \frac{\partial h}{\partial p_i}.$$

Hence,

$$\mathcal{X}_h = \sum_{i=1}^r \frac{\partial h}{\partial q_i} \mathcal{X}_{q_i} + \sum_{i=1}^r \frac{\partial h}{\partial p_i} \mathcal{X}_{p_i} + \sum_{k=1}^{n-2r} \frac{\partial h}{\partial z_k} \mathcal{X}_{z_k} = \mathcal{Y},$$

which shows that \mathcal{Y} is a Hamiltonian vector field on U . \square

Now, we can turn our attention to the proof of proposition 3.6.

Proof. The fibers of $\mathbf{F} = (f_1, \dots, f_s)$ are compact, so for $i = 1, \dots, r$, the flow $\Phi_{t_i}^{(i)}$ of the Hamiltonian vector field \mathcal{X}_{f_i} is complete and we can define a map,

$$\begin{aligned} \Phi : \mathbf{R}^r \times (\mathbf{T}^r \times B^s) &\rightarrow \mathbf{T}^r \times B^s \\ ((t_1, \dots, t_r), m) &\mapsto \Phi_{t_1}^{(1)} \circ \dots \circ \Phi_{t_r}^{(r)}(m). \end{aligned}$$

Since the vector fields \mathcal{X}_{f_i} are pairwise commuting, the flows $\Phi_{t_i}^{(i)}$ pairwise commute and Φ is an action of \mathbf{R}^r on $\mathbf{T}^r \times B^s$. Since the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at all points, the fibers of \mathbf{F} , which are r -dimensional tori, are the orbits of the action. For $c \in B^s$, let Λ_c denote the lattice of \mathbf{R}^r , which is the isotropy group of any point in $\mathbf{F}^{-1}(c)$; it is the period lattice of the action Φ , restricted to $\mathbf{F}^{-1}(c)$. Notice that if Λ_c is independent of $c \in B^s$, the action Φ descends to an action of $\mathbf{T}^r = \mathbf{R}^r / \Lambda_c$ on $\mathbf{T}^r \times B^s$. We will show in Step 1 below that this independence can be assured after applying a diffeomorphism of $\mathbf{T}^r \times B_0^s$ over B_0^s , where B_0^s is a ball, contained in B^s , and concentric with it. The proof of this step is essentially the same as in the symplectic case; it is called *uniformization of the periods*. Steps 2 and 3 below prove successively that the fundamental vector fields of the obtained torus action are Poisson, respectively Hamiltonian vector fields.

Step 1. The periods of Φ can be uniformized to obtain a torus action of \mathbf{T}^r on $\mathbf{T}^r \times B_0^s$, whose orbits are the fibers of \mathbf{F} (restricted to $\mathbf{T}^r \times B_0^s$).

Let m_0 be an arbitrary point of $\mathbf{F}^{-1}(0)$ and choose a basis $(\lambda_1(0), \dots, \lambda_r(0))$ for the lattice Λ_0 . For a fixed i , with $1 \leq i \leq r$, for m in a neighborhood of m_0 in $\mathbf{T}^r \times B^s$ and for L in a neighborhood of $\lambda_i(0)$ in \mathbf{R}^r , consider the equation $\Phi(L, m) = m$. Since $\mathbf{F}(\Phi(L, m)) = \mathbf{F}(m)$ for all L and m , it is meaningful to write $\Phi(L, m) - m$ and solving the equation $\Phi(L, m) = m$ locally for L amounts to applying the implicit function theorem to the map

$$\mathbf{R}^r \times (\mathbf{T}^r \times B^s) \xrightarrow{\Phi(L, m) - m} \mathbf{T}^r \times B^s \longrightarrow \mathbf{T}^r.$$

Since the action is locally free, the Jacobian condition is satisfied and we get by solving for L around $\lambda_i(0)$ a smooth \mathbf{R}^r -valued function $\lambda_i(m)$, defined for m in a neighborhood W_i of m_0 . Doing this for $i = 1, \dots, r$ and setting

$W := \cap_{i=1}^r W_i$, we have that W is a neighborhood of m_0 , and on W we have functions $\lambda_1(m), \dots, \lambda_r(m)$, with the property that $\Phi(\lambda_i(m), m) = m$ for all $m \in W$ and for all $1 \leq i \leq r$. Thus, $\lambda_1(m), \dots, \lambda_r(m)$ belong to the lattice $\Lambda_{\mathbf{F}(m)}$ for all $m \in W$ and they form a basis when $m = m_0$; by continuity, they form a basis for $\Lambda_{\mathbf{F}(m)}$ for all $m \in W$.

The functions λ_i can be extended to a neighborhood of the torus $\mathbf{F}^{-1}(0)$. In fact, the functions λ_i are \mathbf{F} -basic, hence extend uniquely to \mathbf{F} -basic functions on $\mathbf{F}^{-1}(\mathbf{F}(W))$. We will use in the sequel the same notation λ_i for these extensions and we write $\mathbf{F}^{-1}(\mathbf{F}(W))$ simply as W . Using these functions we define the following smooth map:

$$\begin{aligned} \tilde{\Phi} : \quad \mathbf{R}^r \times W &\rightarrow W \\ ((t_1, \dots, t_r), m) &\mapsto \Phi \left(\sum_{i=1}^r t_i \lambda_i(m), m \right). \end{aligned} \quad (3.2)$$

Since the functions λ_i are \mathbf{F} -basic, the fact that Φ is an action implies that $\tilde{\Phi}$ is an action. The new action has the extra feature that the stabilizer of every point in W is \mathbf{Z}^r . Thus, $\tilde{\Phi}$ induces an action of \mathbf{T}^r on W , which we still denote by $\tilde{\Phi}$. By shrinking W , if necessary, we may assume that W is of the form $\mathbf{F}^{-1}(B_0^s)$, where B_0^s is an open ball, concentric with B^s , and contained in it. Thus we have a torus action

$$\begin{aligned} \tilde{\Phi} : \quad \mathbf{T}^r \times W &\rightarrow W \\ ((t_1, \dots, t_r), m) &\mapsto \Phi \left(\sum_{i=1}^r t_i \lambda_i(m), m \right). \end{aligned}$$

Step 2. The fundamental vector fields of the torus action $\tilde{\Phi}$ are Poisson vector fields.

We denote by $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ the fundamental vector fields of the torus action $\tilde{\Phi}$, constructed in step 1. We need to show that $\mathcal{L}_{\mathcal{Y}_i} \Pi = 0$, or in terms of the Schouten bracket, that $[\mathcal{Y}_i, \Pi] = 0$, for $i = 1, \dots, r$. To do this, we first expand \mathcal{Y}_i in terms of the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$: since the action $\tilde{\Phi}$ leaves the fibers of \mathbf{F} invariant and since the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ span the tangent space to these fibers at every point, we can write

$$\mathcal{Y}_i = \sum_{j=1}^r \lambda_i^j \mathcal{X}_{f_j}. \quad (3.3)$$

Since all Hamiltonian vector fields leave Π invariant,

$$\mathcal{L}_{\mathcal{Y}_i} \Pi = [\mathcal{Y}_i, \Pi] = \sum_{j=1}^r \left[\lambda_i^j \mathcal{X}_{f_j}, \Pi \right] = \sum_{j=1}^r \mathcal{X}_{\lambda_i^j} \wedge \mathcal{X}_{f_j}, \quad (3.4)$$

which we need to show to be equal to zero. Notice that since the coefficients λ_i in the definition of $\tilde{\Phi}$ are \mathbf{F} -basic, the coefficients λ_i^j are also \mathbf{F} -basic, so they are pairwise in involution, and their Hamiltonian vector fields commute

with all Hamiltonian vector fields \mathcal{X}_{f_k} . In particular it follows from (3.4) that $[\mathcal{X}_{f_k}, [\mathcal{Y}_i, \Pi]] = 0$ for $k = 1, \dots, r$. We derive from it and from (3.3), that $[\mathcal{Y}_i, [\mathcal{Y}_i, \Pi]] = 0$, i.e., that the flow of \mathcal{Y}_i preserves $\mathcal{L}_{\mathcal{Y}_i} \Pi$:

$$\begin{aligned} [\mathcal{Y}_i, [\mathcal{Y}_i, \Pi]] &= \left[\sum_{k=1}^r \lambda_i^k \mathcal{X}_{f_k}, [\mathcal{Y}_i, \Pi] \right] = \sum_{k=1}^r [\lambda_i^k, [\mathcal{Y}_i, \Pi]] \wedge \mathcal{X}_{f_k} \\ &= \sum_{j,k=1}^r \mathcal{X}_{f_j} [\lambda_i^k] \mathcal{X}_{f_k} \wedge \mathcal{X}_{\lambda_i^j} + \sum_{j,k=1}^r \mathcal{X}_{\lambda_i^j} [\lambda_i^k] \mathcal{X}_{f_k} \wedge \mathcal{X}_{f_j} \\ &= 0, \end{aligned} \tag{3.5}$$

since any two \mathbf{F} -basic functions are in involution. Hence, $\mathcal{L}_{\mathcal{Y}_i}^2 \Pi = 0$. Since \mathcal{Y}_i is a complete vector field, and has period 1, we can conclude that $\mathcal{L}_{\mathcal{Y}_i} \Pi = 0$ using the following:

Claim. If \mathcal{Y} is a complete vector field of period 1 and P is a bivector field for which $\mathcal{L}_{\mathcal{Y}}^2 P = 0$, then $\mathcal{L}_{\mathcal{Y}} P = 0$.

In order to prove this claim, we let $Q := \mathcal{L}_{\mathcal{Y}} P$ and we denote the flow of \mathcal{Y} by Φ_t . We pick an arbitrary point m and we show that³ $Q_m = 0$. We have for all t that

$$\frac{d}{dt} ((\Phi_t)_* P_{\Phi_{-t}(m)}) = (\Phi_t)_* (\mathcal{L}_{\mathcal{Y}} P)_{\Phi_{-t}(m)} = (\Phi_t)_* Q_{\Phi_{-t}(m)} = Q_m, \tag{3.6}$$

where we used in the last step that the bivector field Q satisfies $\mathcal{L}_{\mathcal{Y}} Q = 0$. By integrating (3.6),

$$(\Phi_t)_* P_{\Phi_{-t}(m)} = P_m + tQ_m.$$

Evaluated at $t = 1$ this yields $Q_m = 0$, since $\Phi_1 = \text{Id}$, as \mathcal{Y} has period 1.

Step 3. The vector fields $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ are Hamiltonian vector fields (with respect to commuting Hamiltonian functions).

According to Step 2, the vector fields $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ are Poisson vector fields. Since they are tangent to the symplectic leaves, according to lemma 3.7, there is a neighborhood of $m \in \mathbf{F}_m$ in W that we can assume to be of the form $\Omega_r \times W_s$, with $\Omega_r \subset \mathbf{T}^r$, $W_s \subset B^s$, on which the vector fields $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ are Hamiltonian vector fields. In other words, there exists functions that we shall denote by h_1, \dots, h_r , defined on W_s , satisfying the relation $\mathcal{Y}_i = \mathcal{X}_{h_i}$ for all $i = 1, \dots, r$. It shall be convenient to denote by W again the open subset $\mathbf{F}^{-1}(W_s)$.

Let $d\mu$ be a Haar measure on \mathbf{T}^r . For all $m' \in W$, we set:

$$U_{m'} := \{t \in \mathbf{T}^r \mid \tilde{\Phi}_t(m') \in W\}$$

³As before, Q_m denotes the bivector Q at the point m .

where, for all $t = (t_1, \dots, t_r) \in \mathbf{T}^r$, $\tilde{\Phi}_t$ is a shorthand for the map $m' \mapsto \tilde{\Phi}(t_1, \dots, t_r, m')$. We then define functions p_i , $i = 1, \dots, r$ on W by:

$$p_i(m') := \frac{1}{\text{vol}(U_{m'})} \int_{t \in U_{m'}} h_i(\tilde{\Phi}_t(m')) d\mu$$

where $\text{vol}(U_{m'})$ stands for the volume with respect to the Haar measure. Their Hamiltonian vector fields can be computed as follows,:

$$\begin{aligned} \mathcal{X}_{p_i}(m') &= \frac{1}{\text{vol}(U_{m'})} \int_{t \in U_{m'}} \mathcal{X}_{h_i \circ \tilde{\Phi}_t}(m') d\mu \\ &= \frac{1}{\text{vol}(U_{m'})} \int_{t \in U_{m'}} d\tilde{\Phi}_t^{-1}(\mathcal{X}_{h_i}(\tilde{\Phi}_t(m'))) d\mu \\ &= \frac{1}{\text{vol}(U_{m'})} \int_{t \in U_{m'}} d\tilde{\Phi}_t^{-1}(\mathcal{Y}_i(\tilde{\Phi}_t(m'))) d\mu \\ &= \frac{1}{\text{vol}(U_{m'})} \int_{t \in U_{m'}} \mathcal{Y}_i(m') d\mu \\ &= \mathcal{Y}_i(m'), \end{aligned} \tag{3.7}$$

(3.8)

where the fact that \mathcal{Y}_i is invariant under $\tilde{\Phi}_t$ has been used to go from the third to the fourth line. The relation $U_{\tilde{\Phi}_{t'}(m')} = \tilde{\Phi}_{t'}(U_{m'})$ for all $t' \in \mathbf{T}^r$, and the invariance property of the Haar measure, imply that the functions p_1, \dots, p_r are invariant under the \mathbf{T}^r -action. In particular, they are in involution for all $i, j = 1, \dots, r$, since

$$\{p_i, p_j\} = \mathcal{Y}_j[p_i] = 0.$$

In conclusion, on the open subset W , the vector fields $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ are the Hamiltonian vector fields of the commuting functions p_1, \dots, p_r . \square

3.4. The existence of action-angle coordinates. We are now ready to formulate and prove the action-angle theorem, for standard Liouville tori in Poisson manifolds.

Theorem 3.8. *Let (M, Π, \mathbf{F}) be an integrable system, where (M, Π) is a Poisson manifold of dimension n and rank $2r$. Suppose that \mathcal{F}_m is a standard Liouville torus, where $m \in M_r \cap \mathcal{U}_{\mathbf{F}}$. Then there exists \mathbf{R} -valued smooth functions (p_1, \dots, p_{n-r}) and \mathbf{R}/\mathbf{Z} -valued smooth functions $(\theta_1, \dots, \theta_r)$, defined in a neighborhood U of \mathcal{F}_m such that*

- (1) *The functions $(\theta_1, \dots, \theta_r, p_1, \dots, p_{n-r})$ define an isomorphism $U \simeq \mathbf{T}^r \times B^{n-r}$;*
- (2) *The Poisson structure can be written in terms of these coordinates as*

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial \theta_i} \wedge \frac{\partial}{\partial p_i},$$

in particular the functions p_{r+1}, \dots, p_{n-r} are Casimirs of Π (restricted to U);

- (3) The leaves of the surjective submersion $\mathbf{F} = (f_1, \dots, f_{n-r})$ are given by the projection onto the second component $\mathbf{T}^r \times B^{n-r}$, in particular, the functions p_1, \dots, p_{n-r} depend on the functions f_1, \dots, f_{n-r} only.

The functions $\theta_1, \dots, \theta_r$ are called angle coordinates, the functions p_1, \dots, p_r are called action coordinates and the remaining coordinates p_{r+1}, \dots, p_{n-r} are called transverse coordinates.

Proof. We denote $s := n - r$, as before. Since \mathcal{F}_m is a standard Liouville torus, proposition 3.2 and corollary 3.3 imply that there exist on a neighborhood U' of \mathcal{F}_m in M on the one hand Casimir functions p_{r+1}, \dots, p_s and on the other hand \mathbf{F} -basic functions p_1, \dots, p_r , such that $p := (p_1, \dots, p_s)$ and \mathbf{F} define the same foliation on U' , and such that the Hamiltonian vector fields $\mathcal{X}_{p_1}, \dots, \mathcal{X}_{p_r}$ are the fundamental vector fields of a \mathbf{T}^r -action on U' , where each of the vector fields has period 1; the orbits of this torus action are the leaves of the latter foliation. In view of the Carathéodory-Jacobi-Lie theorem (theorem 2.1), there exist on a neighborhood $U'' \subset U'$ of m in M , \mathbf{R} -valued functions $\theta_1, \dots, \theta_r$ such that

$$\Pi = \sum_{j=1}^r \frac{\partial}{\partial \theta_j} \wedge \frac{\partial}{\partial p_j}. \quad (3.9)$$

On U'' , $\mathcal{X}_{p_j} = \frac{\partial}{\partial \theta_j}$, for $j = 1, \dots, r$; since each of these vector fields has period 1 on U' , it is natural to view these functions as \mathbf{R}/\mathbf{Z} -valued functions, which we will do without changing the notation. Notice that the functions $\theta_1, \dots, \theta_r$ are independent and pairwise in involution on U'' , as a trivial consequence of (3.9). In particular, $\theta_1, \dots, \theta_r, p_1, \dots, p_s$ define local coordinates on U'' . In these coordinates, the action of \mathbf{T}^r is given by

$$(t_1, \dots, t_r) \cdot (\theta_1, \dots, \theta_r, p_1, \dots, p_s) = (\theta_1 + t_1, \dots, \theta_r + t_r, p_1, \dots, p_s), \quad (3.10)$$

so that the functions θ_i uniquely extend to smooth \mathbf{R}/\mathbf{Z} -valued functions satisfying (3.10), on $U := \mathbf{F}^{-1}(\mathbf{F}(U''))$, which is an open subset of \mathbf{F}_m in M ; the extended functions are still denoted by θ_i . It is clear that $\{\theta_i, p_j\} = \delta_i^j$ on U , for all $i, j = 1, \dots, r$. Combined with the Jacobi identity, this leads to

$$\mathcal{X}_{p_k}[\{\theta_i, \theta_j\}] = \{\{\theta_i, \theta_j\}, p_k\} = \{\theta_i, \delta_j^k\} - \{\theta_j, \delta_i^k\} = 0,$$

which shows that the Poisson brackets $\{\theta_i, \theta_j\}$ are invariant under the \mathbf{T} -action; but the latter vanish on U'' , hence these brackets vanish on all of U , and we may conclude that on U , the functions $(\theta_1, \dots, \theta_r, p_1, \dots, p_s)$ have independent differentials, so they define a diffeomorphism to $\mathbf{T}^r \times B^s$ where B^s is a (small) ball with center 0, and that the Poisson structure takes in terms of these coordinates the canonical form (3.9), as required. \square

The results of the present section can be applied in particular for a well-known integrable system constructed on a regular coadjoint orbit \mathcal{O} of $\mathfrak{u}(n)^*$, namely the Gelfand-Cetlin integrable system, for which action-angle coordinates are computed explicitly in [11] and [10]. This system can be seen in the Poisson setting, as follows. Dualizing the increasing sequence of Lie algebra inclusions:

$$\mathfrak{u}(1) \subset \cdots \subset \mathfrak{u}(n-1) \subset \mathfrak{u}(n)$$

(where $\mathfrak{u}(k)$ is considered as the left-upper diagonal block of $\mathfrak{u}(k+1)$ for $k = 1, \dots, n-1$), we get a sequence of surjective Poisson maps:

$$\mathfrak{u}(n)^* \longrightarrow \mathfrak{u}(n-1)^* \longrightarrow \cdots \longrightarrow \mathfrak{u}(1)^*$$

The family of functions on $\mathfrak{u}(n)^*$ obtained by pulling-back generators of the Casimir algebras of all the $\mathfrak{u}(k)^*$ for $k = 1, \dots, n$ yields a Liouville integrable system on $\mathfrak{u}(n)^*$. For particular generators, its restriction to an open subset of \mathcal{O} gives the Gelfand-Cetlin system. The invariant manifold is compact, so that theorem 3.8 can be applied and gives the existence of action-angle coordinates, defined not only in a neighborhood of the invariant manifold in \mathcal{O} , but in a neighborhood of the invariant manifold in the ambient space $\mathfrak{u}(n)$. The restriction of these action and angle coordinates to one symplectic leaf \mathcal{O} will give action-angle coordinates on \mathcal{O} , as in [11] or [10].

4. ACTION-ANGLE COORDINATES FOR NON-COMMUTATIVE INTEGRABLE SYSTEMS ON POISSON MANIFOLDS

In this section, we prove the existence of action-angle coordinates in a neighborhood of a compact invariant manifold in the very general context of non-commutative integrable systems.

4.1. Non-commutative integrable systems. We first define precisely what we mean by a non-commutative integrable system on a Poisson manifold, since the definitions in the literature [3, 9, 8] are only given in the case of a symplectic manifold. See the appendix for a more intrinsic version of this definition.

Definition 4.1. Let (M, Π) be a Poisson manifold. An s -tuple of functions $\mathbf{F} = (f_1, \dots, f_s)$ is said to be a *non-commutative integrable system* of rank r on (M, Π) if

- (1) f_1, \dots, f_s are independent (i.e. their differentials are independent on a dense open subset of M);
- (2) The functions f_1, \dots, f_r are in involution with the functions f_1, \dots, f_s ;
- (3) $r + s = \dim M$;
- (4) The Hamiltonian vector fields of the functions f_1, \dots, f_r are linearly independent at some point of M .

We denote the subset of M where the differentials df_1, \dots, df_s (resp. where the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$) are independent by $\mathcal{U}_{\mathbf{F}}$ (resp. by $M_{\mathbf{F},r}$). Notice that $2r \leq \text{Rk } \Pi$, as a consequence of (4).

If (M, Π, \mathbf{F}) is a Liouville integrable system (definition 3.1), then it is clear that the components (f_1, \dots, f_s) of \mathbf{F} can be ordered such that \mathbf{F} is a non-commutative integrable system of rank $\frac{1}{2}\text{Rk } \Pi$. Thus, the notion of a non-commutative integrable system on a Poisson manifold (M, Π) generalizes the notion of a Liouville integrable system on (M, Π) . For simplicity, we often refer in this section to the case of a Liouville integrable system as the *commutative case*.

4.2. Standard Liouville tori for non-commutative integrable systems. Let \mathbf{F} be a non-commutative integrable system of rank r on a Poisson manifold (M, Π) of dimension n . The open subsets $\mathcal{U}_{\mathbf{F}}$ and $M_{\mathbf{F},r}$ are preserved by the flow of each of the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ since each of the functions f_1, \dots, f_r is in involution with all the functions f_1, \dots, f_s . On the non-empty open subset $M_{\mathbf{F},r} \cap \mathcal{U}_{\mathbf{F}}$ of M , the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ define a (regular) distribution \mathcal{D} of rank r . Since the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ commute pairwise, the distribution \mathcal{D} is integrable, and its integral manifolds are the leaves of a (regular) foliation \mathcal{F} . The leaf through $m \in M$ is denoted by \mathcal{F}_m , and called the *invariant manifold through m* of \mathbf{F} . As in the commutative case, we are only interested in the case where \mathcal{F}_m is compact. Under this assumption, \mathcal{F}_m is a compact r -dimensional manifold, equipped with r independent commuting vector fields, hence it is diffeomorphic to an r -dimensional torus \mathbf{T}^r ; then \mathcal{F}_m is called a *standard Liouville torus* of \mathbf{F} . Proposition 3.2 takes in the general situation of a non-commutative integrable system formally the same form, but with the understanding that r now stands for the rank of \mathbf{F} (rather than half the rank of the Poisson structure), as stated in the following proposition⁴.

Proposition 4.2. *Suppose that \mathcal{F}_m is a standard Liouville torus of a non-commutative integrable system \mathbf{F} of rank r on an n -dimensional Poisson manifold (M, Π) . There exists an open subset $U \subset M_{\mathbf{F},r} \cap \mathcal{U}_{\mathbf{F}}$, containing \mathcal{F}_m , and there exists a diffeomorphism $\phi : U \simeq \mathbf{T}^r \times B^{n-r}$, which takes the foliation \mathcal{F} to the foliation, defined by the fibers of the canonical projection $p_B : \mathbf{T}^r \times B^{n-r} \rightarrow B^{n-r}$, leading to the following commutative diagram.*

$$\begin{array}{ccccc}
 \mathcal{F}_m & \hookrightarrow & U & \xrightarrow[\simeq]{\phi} & \mathbf{T}^r \times B^{n-r} \\
 & & \downarrow \mathbf{F}|_U & \nearrow p_B & \\
 & & B^{n-r} & &
 \end{array}$$

⁴Recall that B^{n-r} is a ball of dimension $n - r$.

4.3. Standard Liouville tori and Hamiltonian actions. According to proposition 4.2, the study of a non-commutative integrable system (M, Π, \mathbf{F}) of rank r in the neighborhood of a standard Liouville torus amounts to the study of the non-commutative integrable system $(\mathbf{T}^r \times B^{n-r}, \Pi_0, p_B)$ of rank r , where Π_0 is a Poisson structure on $\mathbf{T}^r \times B^{n-r}$ and the map $p_B : \mathbf{T}^r \times B^{n-r} \rightarrow B^{n-r}$ is the projection onto the second factor. We write the latter integrable system in the sequel as $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ and we denote the components of \mathbf{F} by $\mathbf{F} = (f_1, \dots, f_s)$ where $s := n - r$, as before. We may assume that the first r vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent on $\mathbf{T}^r \times B^s$, as shown in the following lemma, the proof of which goes along the same lines as the proof of lemma 3.5.

Lemma 4.3. *Let $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ be a non-commutative integrable system of rank r , where $\mathbf{F} : \mathbf{T}^r \times B^s \rightarrow B^s$ denotes the projection onto the second component. Let $m \in \mathbf{T}^r \times \{0\}$ and suppose that the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at m . There exists a ball $B_0^s \subset B^s$, centered at 0, such that $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are linearly independent at every point of $\mathbf{T}^r \times B_0^s$.*

One useful consequence of the fact that the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent on $M := \mathbf{T}^r \times B^s$ is that a function $g \in C^\infty(M)$ is \mathbf{F} -basic if and only if $\mathcal{X}_{f_i}[g] = 0$ for $i = 1, \dots, r$. Indeed, g is \mathbf{F} -basic if and only if g is constant on all fibers of \mathbf{F} , and all tangent spaces to these fibers are spanned by the vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$.

We now come to an important difference between the commutative and the non-commutative case, which is related to the nature of the map \mathbf{F} . In the commutative case, two \mathbf{F} -basic functions on $\mathbf{T}^r \times B^s$ are in involution, $\{g \circ \mathbf{F}, h \circ \mathbf{F}\} = 0$ for all $g, h \in C^\infty(B^s)$. Said differently,

$$\mathbf{F} : (\mathbf{T}^r \times B^s, \Pi) \rightarrow (B^s, 0),$$

is a Poisson map, where B^s is equipped with the trivial Poisson structure. The generalization to the non-commutative case is that B^s admits a Poisson structure (non-zero in general), such that \mathbf{F} is a Poisson map. This Poisson structure is constructed by the following (classical) trick: for every pair of functions $g, h \in C^\infty(B^s)$ we have in view of the Jacobi identity, for all $i = 1, \dots, r$,

$$\mathcal{X}_{f_i}[\{g \circ \mathbf{F}, h \circ \mathbf{F}\}] = \{\mathcal{X}_{f_i}[g \circ \mathbf{F}], h \circ \mathbf{F}\} + \{g \circ \mathbf{F}, \mathcal{X}_{f_i}[h \circ \mathbf{F}]\} = 0,$$

so that $\{g \circ \mathbf{F}, h \circ \mathbf{F}\}$ is \mathbf{F} -basic, namely $\{g \circ \mathbf{F}, h \circ \mathbf{F}\} = \{g, h\}_B \circ \mathbf{F}$ for some function $\{g, h\}_B \in C^\infty(B^s)$. It is clear that this defines a Poisson structure $\Pi_B = \{\cdot, \cdot\}_B$ on B^s and that

$$\mathbf{F} : (\mathbf{T}^r \times B^s, \Pi) \rightarrow (B^s, \Pi_B)$$

is a Poisson map. This Poisson structure leads to a special class of \mathbf{F} -basic functions, which play an important role in the non-commutative case, defined as follows.

Definition 4.4. A smooth function h on $\mathbf{T}^r \times B^s$ is said to be a *Casimir-basic function*, or simply a *Cas-basic function* if there exists a Casimir function g on (B^s, Π_B) , such that $h = g \circ \mathbf{F}$.

A characterization and the main properties of Cas-basic functions are given in the following proposition.

Proposition 4.5. *Let \mathbf{F} be a non-commutative integrable system on a Poisson manifold (M, Π) , where $M = \mathbf{T}^r \times B^s$ and \mathbf{F} is projection on the second component. It is assumed that the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at every point of M .*

- (1) *If $g \in C^\infty(M)$, then g is Cas-basic if and only g is in involution with every function which is constant on the fibers of \mathbf{F} ;*
- (2) *Every pair of Cas-basic functions on M is in involution;*
- (3) *If g is Cas-basic, then its Hamiltonian vector field \mathcal{X}_g on M is of the form $\mathcal{X}_g = \sum_{i=1}^r \psi_i \mathcal{X}_{f_i}$, where each ψ_i is a Cas-basic function on M .*

Proof. Suppose that $g \in C^\infty(M)$ is in involution with every function which is constant on all fibers of \mathbf{F} . Then $\mathcal{X}_{f_i}[g] = \{g, f_i\} = 0$ for $i = 1, \dots, r$, hence g is \mathbf{F} -basic, $g = h \circ \mathbf{F}$ for some function h on B^s . If $k \in C^\infty(B^s)$, then $k \circ \mathbf{F}$ is constant on the fibers of \mathbf{F} , so that

$$\{h, k\}_B \circ \mathbf{F} = \{g, k \circ \mathbf{F}\} = 0,$$

where we have used that \mathbf{F} is a Poisson map. It follows that $\{h, k\}_B = 0$ for all functions k on B^s , hence that $g (= h \circ \mathbf{F})$ is Cas-basic. This shows one implication of (1), the other one is clear. (2) is an easy consequence of (1). Consider now the Hamiltonian vector field \mathcal{X}_g of a Cas-basic function g on M . In view of (1), $\mathcal{X}_g[h] = \{h, g\} = 0$ for every function h which is constant on the fibers of \mathbf{F} , hence \mathcal{X}_g is tangent to the fibers of \mathbf{F} . Since the fibers of \mathbf{F} are spanned at every point by the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$, there exist smooth functions ψ_1, \dots, ψ_r on M , such that

$$\mathcal{X}_g = \sum_{i=1}^r \psi_i \mathcal{X}_{f_i}.$$

The functions ψ_i are \mathbf{F} -basic, because $\mathcal{X}_h[\psi_i] = 0$ for every function h which is constant on the fibers of \mathbf{F} . Indeed, for such a function h , we have that $\{g, h\} = 0$ and $\{f_i, h\} = 0$ for $i = 1, \dots, r$, so that

$$0 = \mathcal{X}_{\{g, h\}} = [\mathcal{X}_h, \mathcal{X}_g] = \sum_{i=1}^r (\mathcal{X}_h[\psi_i] \mathcal{X}_{f_i} + \psi_i [\mathcal{X}_h, \mathcal{X}_{f_i}]) = \sum_{i=1}^r \mathcal{X}_h[\psi_i] \mathcal{X}_{f_i}$$

and the result follows from the independence of $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$. \square

Now, we can give a proposition that generalizes proposition 3.2 to the non-commutative setting, which has formally the same shape up to the fact that r , formerly half of the rank of the Poisson structure Π , stands now for

rank of the non-commutative integrable system, and up to the fact that the functions λ_i^j that appear below, are now proved to be Cas-basic, and not simply \mathbf{F} -basic.

Proposition 4.6. *Let $(\mathbf{T}^r \times B^s, \Pi, \mathbf{F})$ be an non-commutative integrable system of rank r , where $\mathbf{F} = (f_1, \dots, f_s)$ is projection on the second component. There exists a ball $B_0^s \subset B^s$, also centered at 0, and there exist Cas-basic functions λ_i^j , such that the r vector fields $\mathcal{Y}_i := \sum_{j=1}^r \lambda_i^j \mathcal{X}_{f_j}$, ($i = 1, \dots, r$), are the fundamental vector fields of a Hamiltonian torus action of \mathbf{T}^r on $\mathbf{T}^r \times B_0^s$.*

We can now turn our attention to the proof of proposition 4.6.

Proof. As in Step 1 of the proof of proposition 3.6, we obtain the existence of a family of \mathbf{R}^r -valued \mathbf{F} -basic functions $\lambda_1, \dots, \lambda_r$ such that $\tilde{\Phi}$, defined as in (3.2), induces a \mathbf{T}^r -action on $\mathbf{T}^r \times B_0^s$, where B_0^s is an s -dimensional ball, contained in B^s . As in Step 2, we expand the fundamental vector fields $\mathcal{Y}_1, \dots, \mathcal{Y}_r$ of the action in terms of the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$,

$$\mathcal{Y}_i = \sum_{j=1}^r \lambda_i^j \mathcal{X}_{f_j}.$$

The proof that the vector fields \mathcal{Y}_i are Poisson vector fields requires an extra argument: we show that the relations $\mathcal{X}_{f_i}[\lambda_i^k] = 0 = \mathcal{X}_{\lambda_i^j}[\lambda_i^k] = 0$ which were used in (3.5) still hold, by showing that the functions λ_i^j are Cas-basic (recall that Cas-basic functions are in involution). To do this, it suffices to show that if a vector field on $\mathbf{T}^r \times B_0^s$ of the form $Z = \sum_{i=1}^r \psi_i \mathcal{X}_{f_i}$ is periodic of period 1, then each of the coefficients ψ_i is Cas-basic. Let Z be such a vector field and consider

$$Z_0 := \sum_{i=1}^r \psi_i(m) \mathcal{X}_{f_i},$$

where m is an arbitrary point in $\mathbf{T}^r \times B_0^s$. Then the restriction of Z_0 to $\mathbf{F}^{-1}(\mathbf{F}(m))$ is periodic of period 1. Let h be an \mathbf{F} -basic function on $\mathbf{T}^r \times B_0^s$, and let us denote the (local) flow of \mathcal{X}_h by Φ_t . Since

$$[\mathcal{X}_h, Z_0] = \sum_{i=1}^r \psi_i(m) [\mathcal{X}_h, \mathcal{X}_{f_i}] = 0,$$

for $|t|$ sufficiently small, the flow of Z_0 starting from $\Phi_t(m)$ is also periodic of period 1. Since the coefficients of Z are the unique continuous functions such that $Z = Z_0$ on $\mathbf{F}^{-1}(\mathbf{F}(m))$ and such that the flow of Z from every point has period 1, it follows that $\psi_i(\Phi_t(m)) = \psi_i(m)$ for $|t|$ sufficiently small. Taking the limit $t \mapsto 0$ yields that $\mathcal{X}_h[\psi_i] = 0$ for every \mathbf{F} -basic function on $\mathbf{T}^r \times B_0^s$. Thus, ψ_i is Cas-basic, for $i = 1, \dots, r$. so that the

proof of Step 2 remains valid, amounting to the fact that the vector fields \mathcal{Y}_i on W are Poisson vector fields, $\mathcal{L}_{\mathcal{Y}_i}\Pi = 0$, which leads in view of (3.4) to

$$\sum_{j=1}^r \mathcal{X}_{\lambda_i^j} \wedge \mathcal{X}_{f_j} = 0. \quad (4.1)$$

We show that these vector fields are Hamiltonian, where the Hamiltonians can be taken as \mathbf{F} -basic functions. The key point is that all coordinates which appear all along this step should now be taken with respect to coordinates adapted to f_1, \dots, f_r . More precisely, we choose some $m \in \mathbf{T}^r \times B_0^s$ in $\mathbf{F}^{-1}(0)$, and we construct in some neighborhood W'_0 of m a system of coordinates

$$(f_1, g_1, \dots, f_r, g_r, z_1, \dots, z_{n-2r})$$

in which the Poisson structure takes the form given in equation (2.1). Of course, the functions z_1, \dots, z_{n-2r} are \mathbf{F} -basic again (and therefore depend on f_1, \dots, f_s only), so that they can be defined in $p^{-1}(p(W'_0))$, an open subset which we also call W'_0 for the sake of simplicity. As before, we make no notational distinction between the functions $f_1, \dots, f_r, z_1, \dots, z_{n-2r}$, considered as functions on $p(W'_0) \subset B^{n-r}$, and the functions $f_1, \dots, f_r, z_1, \dots, z_{n-2r}$ themselves, defined on W'_0 .

In view of Proposition 4.5(3), in the previous system of coordinates, we have that, since the functions λ_i^j are Cas-basic,

$$\mathcal{X}_{\lambda_i^j} = \sum_{k=1}^r \left(\frac{\partial \mu_i^j}{\partial f_k} \circ \mathbf{F} \right) \mathcal{X}_{f_k},$$

Hence, (4.1) gives

$$\sum_{1 \leq j < k \leq r} \left(\left(\frac{\partial \mu_i^j}{\partial f_k} - \frac{\partial \mu_i^k}{\partial f_j} \right) \circ \mathbf{F} \right) \mathcal{X}_{f_j} \wedge \mathcal{X}_{f_k} = 0. \quad (4.2)$$

where μ_i^j is defined by $\lambda_i^j = \mu_i^j \circ \mathbf{F}$. Since the vectors fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are linearly independent at all points of W , all coefficients above vanish and we get, for every $i, j, k \in \{1, \dots, r\}$:

$$\frac{\partial \mu_i^j}{\partial f_k} = \frac{\partial \mu_i^k}{\partial f_j}. \quad (4.3)$$

As in the proof of the classical Poincaré lemma, the functions b_1, \dots, b_r on $\mathbf{F}(W)$, defined by

$$b_i = b_i(f_1, \dots, f_s) := \sum_{j=1}^r \int_{t=0}^1 \mu_i^j(t f_1, \dots, t f_r, z_1, \dots, z_{s-r}) f_j \quad (4.4)$$

satisfy

$$\mu_i^j = \frac{\partial b_i}{\partial f_j}, \quad (4.5)$$

for all $1 \leq i, j \leq r$. It leads to the \mathbf{F} -basic functions p_1, \dots, p_r , defined by $p_i := b_i \circ \mathbf{F}$, for $i = 1, \dots, r$.

Since the Poisson structure on B^s depends only on the variables z_1, \dots, z_s , the map $(f_1, \dots, f_r, z_1, \dots, z_{s-r}) \mapsto (tf_1, \dots, tf_r, z_1, \dots, z_{s-r})$ is Poisson for all $t \in [0, 1]$. Therefore, the function $\mu_i^j(tf_1, \dots, tf_r, z_1, \dots, z_{s-r})$ is a Casimir function, and the functions b_1, \dots, b_r , which are obtained by integration (w.r.t. t) of these functions, are also Casimir functions. Hence, the functions defined by $p_i := b_i \circ \mathbf{F}$ are Cas-basic. The Hamiltonian vector field of p_i is, in view of in view of Proposition 4.5(3), (4.5) and (3.3), given by

$$\mathcal{X}_{p_i} = \mathcal{X}_{b_i \circ \mathbf{F}} = \sum_{j=1}^r \left(\frac{\partial b_i}{\partial f_j} \circ \mathbf{F} \right) \mathcal{X}_{f_j} = \sum_{j=1}^r \left(\mu_i^j \circ \mathbf{F} \right) \mathcal{X}_{f_j} = \sum_{j=1}^r \lambda_i^j \mathcal{X}_{f_j} = \mathcal{Y}_i. \quad (4.6)$$

This shows that each one of the vector fields \mathcal{Y}_i is a Hamiltonian vector field on W . This completes the proof. \square

4.4. The existence of action-angle coordinates. We finally get to the action-angle theorem, for standard Liouville tori of a non-commutative integrable system.

Theorem 4.7. *Let (M, Π) be a Poisson manifold of dimension n , equipped with a non-commutative integrable system $\mathbf{F} = (f_1, \dots, f_s)$ of rank r , and suppose that \mathcal{F}_m is a standard Liouville torus, where $m \in M_{\mathbf{F}, r} \cap \mathcal{U}_{\mathbf{F}}$. Then there exist \mathbf{R} -valued smooth functions $(p_1, \dots, p_r, z_1, \dots, z_{s-r})$ and \mathbf{R}/\mathbf{Z} -valued smooth functions $(\theta_1, \dots, \theta_r)$, defined in a neighborhood U of \mathcal{F}_m , and functions such that*

- (1) *The functions $(\theta_1, \dots, \theta_r, p_1, \dots, p_r, z_1, \dots, z_{s-r})$ define an isomorphism $U \simeq \mathbf{T}^r \times B^s$;*
- (2) *The Poisson structure can be written in terms of these coordinates as*

$$\Pi = \sum_{i=1}^r \frac{\partial}{\partial \theta_i} \wedge \frac{\partial}{\partial p_i} + \sum_{k,l=1}^{s-r} \phi_{k,l}(z) \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_l};$$

- (3) *The leaves of the surjective submersion $\mathbf{F} = (f_1, \dots, f_s)$ are given by the projection onto the second component $\mathbf{T}^r \times B^s$, in particular, the functions $p_1, \dots, p_r, z_1, \dots, z_{s-r}$ depend on the functions f_1, \dots, f_s only.*

The functions $\theta_1, \dots, \theta_r$ are called angle coordinates, the functions p_1, \dots, p_r are called action coordinates and the remaining coordinates z_1, \dots, z_{s-r} are called transverse coordinates.

Proof. Conditions (1) and (2), in view of lemma 3.5, propositions 4.2 and 3.6 imply that there exist on a neighborhood U' of \mathcal{F}_m in M on the one hand \mathbf{F} -basic functions z_1, \dots, z_{s-r} and on the other hand Cas-basic functions

p_1, \dots, p_r , such that

$$p := (p_1, \dots, p_r, z_1, \dots, z_{s-r})$$

and \mathbf{F} define the same foliation on U' , and such that the Hamiltonian vector fields $\mathcal{X}_{p_1}, \dots, \mathcal{X}_{p_r}$ are the fundamental vector fields of a \mathbf{T}^r -action on U' , where each has period 1; the orbits of this torus action are the leaves of the latter foliation. In view of theorem 2.1, there exist on a neighborhood $U'' \subset U'$ of m in M , \mathbf{R} -valued functions $\theta_1, \dots, \theta_r$ such that

$$\Pi = \sum_{j=1}^r \frac{\partial}{\partial \theta_j} \wedge \frac{\partial}{\partial p_j} + \sum_{k,l=1}^{s-r} \phi_{k,l}(z) \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_l}.$$

The end of the proof goes along the same lines as the end of the proof of theorem 3.8. \square

5. APPENDIX: NON-COMMUTATIVE INTEGRABILITY ON POISSON MANIFOLDS

In the symplectic context, the terms superintegrability, non-commutative integrability, degenerate integrability, generalized Liouville integrability and Mischenko-Fomenko integrability refer to the case when the Hamiltonian flow admits more independent constants of motions than half the dimension of the symplectic manifold [3, 8, 9, 17, 16]. All these names correspond to notions which are equivalent, at least locally. Similarly, the definition of a non-commutative integrable system on a Poisson manifold, which we have given in section 4 (definition 4.1) admits different locally equivalent formulations, which each have their own flavor. We illustrate this in this appendix, by giving an abstract geometrical formulation in terms of foliations, and a concrete geometrical formulation in terms of Poisson maps.

For both geometrical formulations, the notion of polarity in Poisson geometry is a key element. Let m be an arbitrary point of a Poisson manifold (M, Π) . The *polar* of a subspace $\Sigma \subset T_m^*M$ is the subspace $\Sigma^{pol} \subset T_m^*M$, defined by

$$\Sigma^{pol} := \{\xi \in T_m^*M \mid \Pi_m(\xi, \Sigma) = 0\}.$$

Notice that the polar of Σ^{pol} can be strictly larger than Σ , because Π_m may have a non-trivial kernel. When $\Sigma = \Sigma^{pol}$, we say that Σ is a Lagrangian subspace.

Let \mathcal{F} and \mathcal{G} be two foliations on the same Poisson manifold (M, Π) . For $m \in M$ we denote by $T_m^\perp \mathcal{F}$ the subspace of T_m^*M , consisting of all covectors which annihilate $T_m \mathcal{F}$, the tangent space to the leaf of \mathcal{F} , passing through m . If \mathcal{F} is defined around m by functions f_1, \dots, f_s , then $T_m^\perp \mathcal{F}$ is spanned by $d_m f_1, \dots, d_m f_s$. We say that \mathcal{F} is *polar* to \mathcal{G} if $T_m^\perp \mathcal{F} = (T_m^\perp \mathcal{G})^{pol}$, for every $m \in M$; also, \mathcal{F} is said to be a *Lagrangian foliation* if \mathcal{F} is polar to \mathcal{F} .

Definition 5.1. Let (M, Π) be a Poisson manifold. An *abstract non-commutative integrable system* of rank r is given by a pair $(\mathcal{F}, \mathcal{G})$ of foliations on M , satisfying

- (1) \mathcal{F} is of rank r and \mathcal{G} is of corank r ;
- (2) \mathcal{F} is contained in \mathcal{G} (i.e., each leaf of \mathcal{F} is contained in a leaf of \mathcal{G});
- (3) \mathcal{F} is polar to \mathcal{G} .

This definition generalizes the definition of an *abstract integrable system* on (M, Π) , which is simply a Lagrangian foliation \mathcal{F} on M .

In the following proposition we prove the precise relation between definitions 4.1 and 5.1.

Proposition 5.2. *Let (M, Π) be a Poisson manifold.*

- (1) *If $\mathbf{F} = (f_1, \dots, f_s)$ is a non-commutative integrable system of rank r on (M, Π) , then on $\mathcal{U}_{\mathbf{F}} \cap M_{\mathbf{F}, r}$ the pair of foliations $(\mathcal{F}, \mathcal{G})$, defined by $\mathcal{F} := \text{fol}(f_1, \dots, f_s)$ and $\mathcal{G} := \text{fol}(f_1, \dots, f_r)$ is an abstract non-commutative integrable system of rank r ;*
- (2) *Given $(\mathcal{F}, \mathcal{G})$ an abstract non-commutative integrable system of rank r on (M, Π) , there exists for every m in M a neighborhood U in M , and functions $\mathbf{F} = (f_1, \dots, f_s)$ on U , such that \mathbf{F} is a non-commutative integrable system of rank r on U .*

Proof. (1) Recall from paragraph 4.1 that the open subsets $\mathcal{U}_{\mathbf{F}}$ and $M_{\mathbf{F}, r}$ of M are defined by

$$\begin{aligned} \mathcal{U}_{\mathbf{F}} &:= \{m \in M \mid d_m f_1 \wedge d_m f_2 \wedge \dots \wedge d_m f_s \neq 0\}, \\ M_{\mathbf{F}, r} &:= \{m \in M \mid \mathcal{X}_{f_1}, \mathcal{X}_{f_2}, \dots, \mathcal{X}_{f_r} \text{ are independent at } m\}. \end{aligned}$$

On $\mathcal{U}_{\mathbf{F}} \cap M_{\mathbf{F}, r}$ the functions f_1, \dots, f_r define a foliation \mathcal{G} of corank r ; similarly, the functions f_1, \dots, f_s define a foliation \mathcal{F} on it of rank r (since $r + s = \dim M$). Obviously, \mathcal{F} is contained in \mathcal{G} . The condition that $\{f_i, f_j\} = 0$ for all $1 \leq i \leq r$ and $1 \leq j \leq s$, implies that the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are tangent to \mathcal{F} at every point. For all $m \in \mathcal{U}_{\mathbf{F}} \cap M_{\mathbf{F}, r}$, the Hamiltonian vector fields $\mathcal{X}_{f_1}, \dots, \mathcal{X}_{f_r}$ are independent at m , hence they span $T_m \mathcal{F}$. It follows that

$$\begin{aligned} (T_m^\perp \mathcal{G})^{\text{pol}} &= \{\xi \in T_m^* M \mid \Pi_m(\xi, d_m f_i) = 0 \text{ for } i = 1, \dots, r\} \\ &= \{\xi \in T_m^* M \mid \xi(\mathcal{X}_{f_i}(m)) = 0 \text{ for } i = 1, \dots, r\} = T_m^\perp \mathcal{F}. \end{aligned}$$

It follows that \mathcal{F} is polar to \mathcal{G} , hence $(\mathcal{F}, \mathcal{G})$ is an abstract non-commutative integrable system.

(2) Let m be an arbitrary point of M . In a neighborhood U of m , there exist smooth functions f_1, \dots, f_s , such that the level sets of f_1, \dots, f_s and of f_1, \dots, f_r define foliations, which coincide with \mathcal{F} and \mathcal{G} on U . Since \mathcal{F} is polar to \mathcal{G} , the functions f_1, \dots, f_r are in involution with the functions f_1, \dots, f_s and the Hamiltonian vector fields of the functions f_1, \dots, f_r are

linearly independent at all points of U . It follows that $\mathbf{F} := (f_1, \dots, f_s)$ is a non-commutative integrable system of rank r on U . \square

When both foliations \mathcal{F} and \mathcal{G} are given by fibrations $\mathbf{F} : M \rightarrow P$ and $\mathbf{G} : M \rightarrow L$ respectively, we have a commutative diagram of submersive Poisson maps:

$$\begin{array}{ccc} (M, \Pi) & \xrightarrow{\mathbf{G}} & (L, \Pi_L) \\ \mathbf{F} \downarrow & \swarrow & \\ (P, \Pi_P) & & \end{array} \quad (5.1)$$

where Π_L is the zero Poisson structure on L . Moreover, item (3) in definition 5.1 amounts for every $m \in M$ to the equality:

$$\mathbf{F}^*(T_{\mathbf{F}(m)}^*P) = (\mathbf{G}^*(T_{\mathbf{G}(m)}^*L))^{pol}. \quad (5.2)$$

Conversely, it is clear that we have the following proposition:

Proposition 5.3. *Suppose that (5.1) is a commutative diagram of submersive Poisson maps, where L has dimension r and is equipped with the zero Poisson structure Π_L , and P has dimension $\dim M - r$. If (5.2) holds for every $m \in M$, then the pair of foliations $(\mathcal{F}, \mathcal{G})$ defined on M by \mathbf{F} and \mathbf{G} is an abstract non-commutative integrable system of rank r on (M, Π) .*

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